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High spatial resolution Galactic 3D extinction mapping with IPHAS

Stuart E. Sale,1* J. E. Drew,1,2 Y. C. Unruh,1 M.J. Irwin,3 C. Knigge,4 S. Phillipps,5 A. A. Zijlstra,6 B. T. Gänscicke,7 R. Greimel,8 P. J. Groot,9 A. Mampaso,10 R. A. H. Morris,5 R. Napiwotzki,2 D. Steeghs7,11 and N. A. Walton3

1Astrophysics Group, Imperial College London, Blackett Laboratory, Prince Consort Road, London SW7 2AZ
2Centre for Astrophysics Research, STRI, University of Hertfordshire, College Lane Campus, Hatfield AL10 9AB
3Institute of Astronomy, Madingley Road, Cambridge CB3 0HA
4School of Physics & Astronomy, University of Southampton, Southampton SO17 1BJ
5Astrophysics Group, Department of Physics, Bristol University, Tyndall Avenue, Bristol BS8 1TL
6Jodrell Bank Centre for Astrophysics, Alan Turing Building, The University of Manchester, Oxford Street, Manchester M13 9PL
7Department of Physics, University of Warwick, Coventry CV4 7AL
8Institut für Physik, Karl-Franzens Universität Graz, Universitätsplatz 5, 8010 Graz, Austria
9Department of Astrophysics/MAPP, Radboud University Nijmegen, PO Box 9010, 6500 GL Nijmegen, the Netherlands
10Instituto de Astrofísica de Canarias, Via Láctea s/n, E38200 La Laguna, Santa Cruz de Tenerife, Spain
11Harvard–Smithsonian Center for Astrophysics, 60 Garden Street, Cambridge, MA 02138, USA

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ABSTRACT

We present an algorithm (MEAD, for ‘Mapping Extinction Against Distance’) which will determine intrinsic \((r' - i')\) colour, extinction, and distance for early-A to K4 stars extracted from the IPHAS \(r'/i'/H\alpha\) photometric data base. These data can be binned up to map extinction in three dimensions across the northern Galactic plane. The large size of the IPHAS data base (~200 million unique objects), the accuracy of the digital photometry it contains and its faint limiting magnitude \((r' \sim 20)\) allow extinction to be mapped with fine angular (~10 arcmin) and distance (~0.1 kpc) resolution to distances of up to 10 kpc, outside the solar circle. High reddening within the solar circle on occasion brings this range down to ~2 kpc. The resolution achieved, both in angle and depth, greatly exceeds that of previous empirical 3D extinction maps, enabling the structure of the Galactic Plane to be studied in increased detail. MEAD accounts for the effect of the survey magnitude limits, photometric errors, unresolved interstellar medium (ISM) substructure and binarity. The impact of metallicity variations, within the range typical of the Galactic disc is small. The accuracy and reliability of MEAD are tested through the use of simulated photometry created with Monte Carlo sampling techniques. The success of this algorithm is demonstrated on a selection of fields and the results are compared to the literature.

Key words: methods: miscellaneous – surveys – stars: general – dust, extinction – ISM: structure – Galaxy: disc.

1 INTRODUCTION

The INT/WFC Photometric H\(\alpha\) Survey of the northern Galactic plane (IPHAS; Drew et al. 2005) is the first comprehensive digital survey of the disc of the Galaxy \((|b| \leq 5^\circ)\), north of the celestial equator. Imaging is performed in the \(r'\), \(i'\) and \(H\alpha\) bands down to \(r' \sim 20\) (10\(r\)). The high-quality photometry from this survey has been shown to enable early-A type stars to be selected very easily, due to their strong \(H\alpha\) absorption (Drew et al. 2008). In this same study, the \((r' - i')\) colours provided by IPHAS were used to determine the extinctions of the A stars selected, and then distances were deduced using photometric parallax. This capability is a specific example of a more general property of the IPHAS: since \((r' - H\alpha)\) correlates strongly with intrinsic \((r' - i')\) colour, the combination of \(r', i'\) and \(H\alpha\) can be used to disentangle intrinsic colour and extinction unambiguously. The aim of this paper is to present a method which extends the approach of Drew et al. (2008) to incorporate a broader range of spectral types and, therefore, many more objects. Then extinction can be successfully mapped at fine angular resolutions out to large distances.

The IPHAS catalogue contains high-quality photometry for ~200 million objects, equating to over 10^7 objects per square degree. Our analysis of a wide variety of IPHAS fields has shown that

*E-mail: s.sale06@imperial.ac.uk

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the data quality allows for accurate determinations of distances and extinctions to the studied objects, with median errors of typically ~100 pc on distance and approximately 0.1 mag of error on the determined extinction. The limiting magnitude of the IPHAS catalogue (r′ ~ 20, 10σ) is sufficient for extinctions to be measured to distances up to ~10 kpc from the Sun.

Jurić et al. (2008) discuss and demonstrate the potential for accurate wide area surveys in analysing the structure of the Milky Way. They utilize the Sloan Digital Sky Survey (SDSS) in order to determine the stellar number density distribution mostly at Galactic latitudes |b| > 25°. As a result of this they are able to easily study the Galactic halo and local scaleheights of the Milky Way’s thick and thin discs, and find localized overdensities. In contrast the IPHAS survey area covers low Galactic latitudes, enabling the Galactic thin disc to be studied in detail, well beyond the solar neighbourhood. The cost associated with this is that extinction, which is largely negligible in the SDSS survey area, becomes a significant concern to the extent that understanding its 3D distribution is a necessary hurdle that must be overcome on the path to studying the structure of the Galactic disc.

Applications of extinction mapping go beyond studies of Galactic structure: a distance–extinction relationship, combined with an estimate of the extinction to an object has often been exploited to give an estimate of the distance to individual objects. Such estimates are of particular use for objects such as planetary nebulae, for which reliable estimates of distance are difficult to obtain (Viironen et al., in preparation).

There is a long history associated with trying to map the distribution of extinction, going back as far as Trumpler (1930) and van de Kamp (1930) who both appreciated that extinction is concentrated near the Galactic plane. Subsequent efforts to map extinction can be broken down into two broad categories: 2D maps of the asymptotic extinction and 3D maps with varying degrees of model input.

Several studies have produced 2D maps of the maximum asymptotic extinction over the sky. Burstein & Heiles (1982) used H1 mapping and galaxy counts, estimating the errors in derived extinctions to be ~10 per cent. Schlegel, Finkbeiner & Davis (1998) provided updated maps based on CUBE and FIRAS measurements of dust emission at 100 μm. The Schlegel et al. (1998) maps have since been widely used, but they warn that their values for |b| < 5° are subject to significant errors, an assertion that has been supported by Arce & Goodman (1999) and Cambrésy, Jarrett & Beichman (2005). More recently Froebrich et al. (2005) have used cumulative star counts from the Two Micron All Sky Survey (2MASS) survey to construct a 2D extinction map of the Galactic plane (|b| < 20°).

3D extinction models have grown progressively more sophisticated, moving from the simple cosecant model (Parenago 1945) to the modern, high-resolution models of Mendez & van Altena (1998), Chen et al. (1999), Drimmel & Spergel (2001) and Amôres & Lépine (2005). Marshall et al. (2006) compared the Besançon Galactic model (Robin et al. 2003), without extinction, to 2MASS observations. The differences between the observed and theoretical colours of predominantly K&M giants were then attributed to extinction. This semi-empirical method is able to map extinction at fine angular resolutions (0.25 × 0.25).

Historically, attempts to empirically map extinction in three dimensions have been constrained by the availability and quality of photometric data. Early studies include Fernie (1962), Eggen (1963), Isserstedt & Schmidt-Kaler (1964), Neckel (1966), Schef- fler (1966, 1967), all of which reached no fainter than V ~ 10 and therefore could only cover relatively limited ranges of up to 1–2 kpc. Also, they all contain fewer than 5000 objects, limiting their mappings to very coarse spatial resolutions. Furthermore, Fitzgerald (1968) found that these works produced ‘varying, and sometimes apparently conflicting results’. Subsequently, Fitzgerald (1968), Lucke (1978) and Neckel, Klare & Sarcard (1980) continued, with similar approaches, but they were still limited by the available photometric catalogues, with the most recent of the three (Neckel et al. 1980) using a catalogue of ~11 000 objects. As a result, they achieved angular resolutions of the order of a few degrees.

Here, we present a new approach to mapping the 3D extinction within the plane of our Galaxy, based on IPHAS photometry. The depth, quantity and quality of this data set allows us to construct a new extinction map with high angular (10 arcmin) and distance (100 pc) resolution out to very large distances (up to 10 kpc). In the present paper, we focus on the algorithm used to construct this map, leaving the map itself to be presented in a separate publication. The algorithm which is used to calculate distance–extinction relationships from IPHAS data (hereafter referred to as MEAD, Mapper of Extinction Against Distance) is discussed in detail in Section 3. In order for it to be used with IPHAS data it is necessary to calibrate this translation of IPHAS photometry into derived quantities (Section 2). Section 4 shows the use of simulated photometry to determine the values of some key parameters used in MEAD and demonstrates its accuracy in the face of a range of possible problems. Finally, Section 5 investigates the use of MEAD on real IPHAS data, showing the power of its approach.

2 DECODING INTRINSIC COLOUR, LUMINOSITY CLASS AND EXTINCTION FROM IPHAS PHOTOMETRY

In order to exploit IPHAS, it is necessary to understand the behaviour of its colour–colour and colour–magnitude planes – specifically the intrinsic colours of normal stars and their response to extinction. To this end Drew et al. (2005) produced simulations of the luminosity class sequences on the IPHAS colour–colour plane using the spectral library of Pickles (1998). In Fig. 1 we provide an example of (r′ − Hα, r′ − i′) data for a survey field with differently reddened simulated main sequences spanning the O9 to M3 spectral type range superposed: this shows how reddening shifts the main sequence (Section 2).
sequence across to the right-hand side, creating a lower edge to the main stellar locus that is well described as the early-A reddening line. Reddening also moves O and B stars to the same colours as A and F stars, though they are still separated in apparent magnitude. For the purpose of emulating the colour behaviour of normal stars, the Pickles (1998) library contains limited numbers of objects that cannot support a full exploration of the available parameter space. In particular, in order to examine the impact of changing metallicity and fine variations in luminosity class, we have recomputed expected IPHAS colours from grids of model atmospheres.

New luminosity class sequences have been obtained for the IPHAS colour–colour and colour–magnitude planes using the Munari et al. (2005) library of ATLAS9 synthetic spectra. Kurucz (2005) discusses some particular limitations of ATLAS9 models, some of which are relevant to this study: ATLAS9 spectra include only an incomplete sample of diatomic molecules and, with the exception of H2O, no triatomic or larger molecules. This inherently leads to deviations from reality, which become significant for late K and all M type stars (Bertone et al. 2004). In particular the absence of VO lines means that Kurucz models are not available for $T_{\text{eff}} < 3500$ K (approximately M4 or later) as they would be particularly inaccurate (Kurucz 2005). Similar problems affect other grids of atmospheres, with the consequence that, for our purposes, there are no reliable alternative model grids at these low temperatures.

### 2.1 Method and underpinning stellar data

So as to use the synthetic spectral libraries to create luminosity class sequences, the classes of the MK system (Morgan, Keenan & Kellman 1943) must be linked to $T_{\text{eff}}, \log g$ and absolute magnitudes $(M_{\text{V}})$. This study adopts the $T_{\text{eff}}$ and log $g$ calibrations of Straižys & Kūrieliene (1981), as well as their absolute magnitude calibrations for all classes except dwarfs, for which we use the data of Houk et al. (1997) based on Hipparchos parallaxes. In Table 1 we give the solar metallicity mapping of intrinsic $(r' - i')$ colour on to main-sequence (MS) absolute magnitude and spectral type that we have adopted, while Fig. 2 shows the relevant Hertzsprung–Russell diagram of the five luminosity classes we use.

All synthetic colours were determined largely as by Drew et al. (2005), with the modest difference that the atmospheric transmission curve at the INT is included in the calculation, so that the total transmission profile is the product of the atmospheric transmission, CCD response and filter transmission curves.

As IPHAS magnitudes are based on the Vega system, an appropriate spectrum of Vega was required to provide the zero-point flux. So as to match spectral resolution (which is necessary to produce accurate Hα magnitudes) the ATLAS9 Vega model spectrum available via kurucz.harvard.edu was used. This assumes $T_{\text{eff}} = 9500$ K and $\log g = 3.80$. It should be noted that there has been much debate over which ATLAS9 spectra best fits observations of Vega. For example, Cohen et al. (1992) and Bohlin (2007) argue that the 9400-K model (as opposed to the 9500-K model used in this paper) is better suited. However, the differences in derived colours are small, $\delta(r' - H\alpha) \approx 0.003$, so the choice from these two models is of little consequence.

For comparison to the synthetic sequences derived in this study, sequences based on libraries of intrinsic (i.e. unreddened or dereddened) empirical spectral energy distributions (SEDs) are employed. At the time of writing there are over 100 electronic libraries available, summarized in the Asiago Data base of Spectrophotometric Data bases (Sordo & Munari 2006, http://web.pd.astro.it/adsd). However, of these only a small proportion cover the wavelength range required and many of those are unsuitable. Once these have been filtered out, the STELIB library (Le Borgne et al. 2003) and the library of Pickles (1998) remain.

### 2.2 Comparisons between colour sequences from synthetic and empirical libraries

Fig. 3 compares the main sequence derived from the synthetic spectra of Munari et al. (2005), to colours derived from empirical spectra. For most spectral types the results from empirical and synthetic spectra agree well. However, for M type stars there is some disagreement. This could be a result of difficulties associated with modelling late-type stars, as noted earlier. A comparison was also performed to sequences derived from the MARCS (Gustafsson et al. 2003) and PHOENIX (Brott & Hauschildt 2005) codes. The MARCS library only

<table>
<thead>
<tr>
<th>$(r' - i')$</th>
<th>$(r' - H\alpha)$</th>
<th>$r'$ absolute magnitude</th>
<th>Spectral type</th>
<th>$T_{\text{eff}}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>-0.047</td>
<td>0.029</td>
<td>0.12</td>
<td>B8</td>
<td>11 510</td>
</tr>
<tr>
<td>-0.028</td>
<td>0.013</td>
<td>0.51</td>
<td>B9</td>
<td>10 400</td>
</tr>
<tr>
<td>-0.006</td>
<td>-0.002</td>
<td>0.80</td>
<td>A0</td>
<td>9600</td>
</tr>
<tr>
<td>0.001</td>
<td>-0.005</td>
<td>1.09</td>
<td>A1</td>
<td>9400</td>
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<td>A2</td>
<td>9150</td>
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<td>-0.008</td>
<td>1.47</td>
<td>A3</td>
<td>8900</td>
</tr>
<tr>
<td>0.060</td>
<td>0.006</td>
<td>1.84</td>
<td>A5</td>
<td>8400</td>
</tr>
<tr>
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<td>8000</td>
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<tr>
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<td>F0</td>
<td>7300</td>
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<tr>
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<td>2.92</td>
<td>F2</td>
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<td>3.37</td>
<td>F5</td>
<td>6500</td>
</tr>
<tr>
<td>0.296</td>
<td>0.202</td>
<td>3.83</td>
<td>F8</td>
<td>6150</td>
</tr>
<tr>
<td>0.318</td>
<td>0.218</td>
<td>4.11</td>
<td>G0</td>
<td>5950</td>
</tr>
<tr>
<td>0.336</td>
<td>0.229</td>
<td>4.39</td>
<td>G2</td>
<td>5800</td>
</tr>
<tr>
<td>0.372</td>
<td>0.252</td>
<td>4.75</td>
<td>G5</td>
<td>5500</td>
</tr>
<tr>
<td>0.406</td>
<td>0.269</td>
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<td>5250</td>
</tr>
<tr>
<td>0.436</td>
<td>0.283</td>
<td>5.58</td>
<td>K0</td>
<td>5050</td>
</tr>
<tr>
<td>0.454</td>
<td>0.291</td>
<td>5.76</td>
<td>K1</td>
<td>4950</td>
</tr>
<tr>
<td>0.472</td>
<td>0.298</td>
<td>6.04</td>
<td>K2</td>
<td>4850</td>
</tr>
<tr>
<td>0.504</td>
<td>0.312</td>
<td>6.20</td>
<td>K3</td>
<td>4700</td>
</tr>
<tr>
<td>0.527</td>
<td>0.322</td>
<td>6.48</td>
<td>K4</td>
<td>4600</td>
</tr>
</tbody>
</table>

**Figure 2.** A Hertzsprung–Russell diagram of the simulated luminosity classes used in this study. The unshaded region of the diagram indicates the intrinsic colour range of interest, which is the range of intrinsic colour that MEAD works on.
covers spectral types from early-A to early-K, but it is in excellent agreement with the results obtained from Munari et al. (2005). On the other hand, the sequences of Brott & Hauschildt (2005) are significantly different for spectral types later than roughly K4. On further examination the differences are almost entirely limited to behaviour in the Hα band. It is worth noting that Gustafsson et al. (2008) demonstrate that a new version of the PHOENIX code, employing the Kurucz line data, performs considerably better than the version employed here. Therefore it is possible that the discrepancies we encounter will not be present in this newer version.

Bertone et al. (2004) finds the ATLAS9 and PHOENIX models which best-fitting intrinsic spectra of known type and list the Teff of the fit. By assuming that the Teff calibration of Straizys & Kurilienė (1981) represents the mean temperature for any given class, it is possible to calculate the standard deviation of the residuals of the Bertone et al. (2004) estimates. This is then an estimate of the combination of the error on the Straizys & Kurilienė (1981) Teff calibration and the natural width of each class. However, allowing for this temperature variation makes no measurable difference to our model sequences.

Unfortunately Bertone et al. (2004) do not give the values of log g for each fit, so it is not possible to repeat this procedure for surface gravity. However, Munari et al. (2005) suggest that the natural width of each class in surface gravity is ~0.25 dex. Applying this spread results in the luminosity class sequences changing from lines to bands in colour–colour and colour–magnitude space. The majority of objects from the Pickles (1998) and STELIB libraries now fall within these bands. Bertone et al. (2004) also demonstrate that the quality of the best fit to the stars in the empirical libraries it uses decreases for later types. This behaviour is again attributable to the poorly understood molecular lines, which dominate the spectra of late-type stars.

### 2.3 The impact of rotational broadening

As might be expected, altering the rotational velocity assumed in the models has negligible effect on the colours. This is as varying rotational velocity will only alter the shape of an unsaturated line and will not affect the strength of absorption or emission. As all the filters used are broad compared to emission or absorption lines, simply altering the line shapes does not change the observed colours. In saturated lines the equivalent width is affected by rotational broadening, but Hα is the only atomic line which produces a significant impact on the photometric colours and it does not saturate, even in A3V stars where absorption is strongest.

### 2.4 The impact of metallicity variation

Given that Straizys & Kurilienė (1981) do not consider the effect of metallicity it is clearly not possible to use the sequences based on it to study the effect of metallicity. However, the library of Pietrinferni et al. (2004) does consider it and so is used in this section. For Munari et al. (2005) models altering metallicity has little effect on IPHAS colour–colour diagrams, a shown by Fig. 4.

Metallicity can, however, have a significant effect on the absolute magnitude of all objects. Fig. 5 demonstrates this for a zero-age main-sequence (ZAMS). As it is not possible to determine the metallicity of the object from IPHAS observations, it is therefore also not possible to uniquely determine the absolute magnitude of an object.

Friel et al. (2002) measured metallicities in low Galactic latitude open clusters, finding no objects with [Fe/H] < −0.94, whilst Carraro et al. (2007) determine the mean metallicity in the outer disc to be [Fe/H] ≈ −0.35. So, observing an object with a metallicity below [Fe/H] = −0.5 in IPHAS would be unusual and metallicities as low as [Fe/H] = −1.82 would be extremely rare. Therefore, the effect of metallicity variations on absolute magnitude will be relatively small in IPHAS observations. Section 4.8 further examines the impact of undiagnosed metallicity variations.

![Figure 3. The simulated main (solid black line) and giant (dashed green line) sequences compared to solar metallicity MS objects from the Pickles (1998) and STELIB (Le Borgne et al. 2003) libraries (red crosses). As with figure 2, the unshaded region of the diagram indicates the intrinsic colour range of interest, used by MEAD.](image)

![Figure 4. ZAMS from the Pietrinferni et al. (2004) library on the colour–colour plane, where the colours have been determined from the appropriate Munari et al. (2005) models. In black is a ZAMS for [Fe/H] = 0, in red a ZAMS for [Fe/H] = −1.00 and in green a ZAMS for [Fe/H] = −1.82.](image)

![Figure 5. ZAMS from the Pietrinferni et al. (2004) library on the colour–magnitude plane, where the colours have been determined from the appropriate Munari et al. (2005) models. The top, in black, is a ZAMS for [Fe/H] = 0. The curve is lowered with decreasing metallicity, in blue is [Fe/H] = −0.40, red [Fe/H] = −1.00 and at the bottom, in green, is [Fe/H] = −1.82.](image)
2.5 Extinction and reddening

It is very important to note that, in the IPHAS colour–colour plane, the reddening vector is at a significant angle with respect to the majority of the main sequence (see Fig. 6). This makes it possible to derive accurate estimates of intrinsic \((r' - i')\) colour and extinction simultaneously. For colours based on other commonly used filter sets such as \(u' g' r' i' z'\) or \(JHK\), the reddening vector is almost parallel to the main sequence, creating degeneracy in the available (intrinsic colour, extinction) solutions. This property of the IPHAS colour–colour plane is a result of the strong intrinsic \((r' - i')\) colour sensitivity of the \((r' - Hz)\) colour, whilst its response to reddening is weak compared to that of broad-band colours. The former property is due to \((r' - Hz)\) being a proxy for the \(Hz\) equivalent width, which itself is strongly dependent on intrinsic \((r' - i')\) colour.

In many applications in astrophysics it is acceptable to treat the ratio \(R_e = A_e/E(B - V)\) as constant across a wide range of objects, so that extinction can easily be calculated from reddening and vice-versa. However, as pointed out by McCall (2004) this is not in general true, as the extinction integrated across a given broad-band filter is a function of the SED of the observed object and the amount and wavelength dependence of the extinction it has experienced. McCall (2004) suggests that monochromatic measures of extinction should be used, in preference to broad-band measures, as they are independent of the observed objects’ SEDs. Following this concept, MEAD measures a monochromatic extinction at 6250 Å \(A_{6250}\). This is near the effective wavelength of the \(r'\) filter in the INT system (i.e. taking into account the WFC and atmospheric response). If the intrinsic colour of the observed object is known it will then be possible to convert to and from more commonly used broad-band measures. In this study, we will refer to monochromatic extinctions in discussions of the simulated photometry, while extinctions derived from real data that are compared with the literature will be presented as broad-band values, \(A_e\). The extinction at \(r'\) is preferred to the extinction in the \(V\) band for the reasons discussed by Cardelli, Clayton & Mathis (1989). Section 4.10 investigates the ability of MEAD to change between monochromatic and broad-band measures of extinction as \(R\) is varied. By choosing to normalize the extinction law to a wavelength in the middle of the range studied the systematic error produced by uncertainty in the value of \(R\) is minimized.

This paper adopts the extinction laws of Fitzpatrick (2004) for the calculation of extinction values in different filters as a function of \(A_{6250}\). Fortunately, this study avoids the problematic ultraviolet region where extinction laws are characterized by several variables, which are uncorrelated with \(R\) (Fitzpatrick & Massa 2007). Here, the focus is on the IR/optical region where the wavelength dependence of extinction is well defined by \(R\) only. Following Savage & Mathis (1979) and Howarth (1983), we assumed that \(R = 3.1\), so as to represent an average Galactic sightline.

The calibration of the broad-band extinctions to \(A_{6250}\) was performed using the Munari et al. (2005) library to represent the Stražys & Kurilienė (1981) sequences. Fitting was performed by linear regression of a quadratic polynomial to the data, over a range of \(0 \leq A_{6250} < 10\), the functions returned, for a band \(X\), are expressed as follows: \(A_X = a_X A_{6250}^2 + b_X A_{6250} + c_X\).

Fig. 6 demonstrates the effect of extinction on several different spectral types in the \((r' - i', r' - Hz)\) plane. Despite being cosmically similar, there are significant differences in the response to extinction of different spectral types. Fig. 7 demonstrates the variation of the coefficient for the leading linear term in the fits. For objects with types in the critical range A3 to K4 \((0.05 \leq (r' - i') < 0.55)\) there is a particularly simple linear relation between this fit coefficient and intrinsic \((r' - i')\) colour, as can also be seen in Fig. 7.

The differing responses to rising extinction of different spectral types are illustrated by the extreme examples of A3V and M4V stars: in Fig. 6 these two types limit the plotted \((r' - Hz)\) range of the main sequence. As more extinction is applied, the \((r' - Hz)\) range spanned shrinks because the A3V star is reddened more quickly in this colour.

3 MEAD: AN ALGORITHM TO DETERMINE EXTINCTION–DISTANCE RELATIONS

3.1 Concept

The basic principle of this paper is that we wish to determine the distance and intervening extinction to a large sample of objects in the IPHAS data base. From the observations, we have three observed parameters for each object, namely the \(r'\), \(i'\) and \(Hz\) magnitudes, with errors on each. In order to determine the distance to an object by photometric parallax, we must determine its absolute magnitude and extinction. The simplest way to estimate absolute magnitude is to determine the intrinsic colour and luminosity class of the object. Thus for each object we have three parameters we wish to determine (extinction, luminosity class and intrinsic colour) and three observed parameters.

As described in Section 2, it is possible to ascertain the spectral class and monochromatic extinction of an object from its position on the colour–colour plane. But, there are two main sources of degeneracy in this process. The first is caused by the fact that reddening
tracks for O, B and early A (A0-2) stars intersect those of later A and F stars. This follows from the fact that Hα absorption peaks in early A stars and (r' − Hα) is strongly correlated with Hα equivalent width (Drew et al. 2005). As discussed in Section 3.3, it transpires that this is not normally a significant source of degeneracy.

The second more important source of degeneracy is luminosity class, which has a significant impact on distance determination. Therefore, to estimate an object’s distance, it is necessary for an estimate of the luminosity class to be determined first. This is, however, not a trivial task, as the different luminosity class sequences behave very similarly on the IPHAS colour–colour plane. We decide on the luminosity class of an object as follows. If two objects of identical intrinsic colours, but different absolute magnitude, are to have the same apparent magnitude the more luminous object must be further away, and is likely to be more heavily reddened. This reddening contrast creates two sequences in a colour–magnitude diagram, as can be seen in Fig. 8, where a selection of mainly F stars are clearly split into dwarf and giant sequences. It is by identifying these split sequences in the colour–magnitude diagram that luminosity class is assigned.

3.2 Details of implementation

Fig. 9 outlines an algorithm that realizes this principle (named MEAD for Mapper of Extinction Against Distance). In the remainder of this section each of the steps in MEAD are described.

Extinction, intrinsic colour and distance are determined simultaneously for all objects in the intrinsic colour range of interest given in Figs 2 and 3. Objects which fall outside this region of the colour–colour plane which could be occupied by objects of the types we are interested in are simply discarded. The discarded objects will include M and late-K type stars, white dwarfs, extragalactic objects and stars exhibiting Hα emission. At the same time errors on the derived quantities are also propagated from the photometric errors. Although determined at the same time as distance, the estimates of extinction and intrinsic colour are almost independent of the luminosity class and can be considered to be determined solely from the colour–colour plane: only very small differences arise from the slight differences between the luminosity class sequences in the colour–colour plane.

The appearance of objects on the extinction–distance plane is complicated by several factors. First, the size of the errors on the estimated values of extinction and distance vary greatly from object to object. Also, these errors are correlated with distance and extinction, as the apparent magnitude of a source becomes fainter with increasing distance or extinction, increased photometric error is to be expected. Finally, because of the finite angular resolution of the fields, there will inevitably be unresolved substructure within the absorbing material in each field analysed, causing an intrinsic and irreducible spread of extinctions at any given distance. These complications are dealt with by assuming that extinction at any given distance is modelled by a distribution other than the delta function: a maximum likelihood estimator is used to determine the value of the parameters that describe the distribution. The choice of family of distributions used here is further discussed in Section 4.4.

IPHAS observations are subject to both bright and faint magnitude limits. The implication of this is that for an object at a given distance, it will only be observed if its extinction also falls between two limits, and when these limits are approached, the observations will start to become incomplete. This would bias any estimates. The nature of the bias is that as the faint cut-off is approached, only stars viewed through lower extinction remain in the sample, while more extinguished objects are lost. Hakkila et al. (1997) note the disruptive effect that this had on previous studies (Fitzgerald 1968; Neckel, Klare & Sarcander 1980; Arenou, Grenon & Gomez 1992). Even at the higher angular resolutions treated here this effect continues to be a problem because the interstellar medium is inhomogeneous down to very small scales. Deshpande (2007) demonstrates that variations in the structure of the interstellar medium (ISM) naturally extend down to at least the scale of tens of au. Therefore, it is necessary to continue to attend to the magnitude limits in this study, even though significantly finer angular resolutions are achievable than those in earlier work.
To deal with this problem, it is necessary to determine which objects could be close to the magnitude limit in distance extinction space, so that they can be excluded when producing an unbiased distance–extinction relationship. To establish which objects are to be excluded, first all the objects are binned in distance to produce a biased distance–distance relationship, for each bin the mean and intrinsic standard deviation of the extinction is found. Then, for each object the maximum \( (d_{\text{max}}) \) and minimum \( (d_{\text{min}}) \) distances for which observations of that type of object would be complete are estimated. These distances occur where the following two equations are satisfied, where \( A_{6250}^{\text{bright}} (d) \) and \( A_{6250}^{\text{faint}} (d) \) correspond to the bright and faint magnitude limits, respectively, and \( \sigma_{d}(d) \) is the intrinsic standard deviation of extinction in the relevant bin:

\[
\bar{A}_{6250}(d_{\text{max}}) + n \sigma_{d}(d_{\text{max}}) = A_{6250}^{\text{faint}}(d),
\]

(1)

\[
\bar{A}_{6250}(d_{\text{min}}) - n \sigma_{d}(d_{\text{min}}) = A_{6250}^{\text{bright}}(d).
\]

(2)

If these equations are satisfied at more than one distance, the largest possible value of \( d_{\text{min}} \) and smallest possible value of \( d_{\text{max}} \) are taken. In equations (1) and (2) the value of \( n \) can be altered. Increasing it will reduce the chance of the bias affecting the data, at the cost of decreasing the number of objects which are binned to produce the distance–extinction relationship, whilst decreasing it will act in the opposite sense. There is no immediately obvious value to adopt for \( n \) and Section 4.5 discusses the use of simulated photometry to find an appropriate value. At the bright end it is assumed that the magnitude range over which observations become incomplete is small, relative to the apparent magnitude sampling, so objects which are closer than \( d_{\text{max}} \) are simply discarded. In contrast, at the faint end where the apparent magnitude sampling is much denser, the magnitude range over which observations become incomplete is significant. Therefore the contribution of each object to the distance and extinction estimates is weighted using a sigmoid function as follows:

weight = \( (1 + \exp(s(\mu - \mu_{\text{max}})))^{-1} \)

(3)

where \( \mu \) is the distance modulus of the object in question, \( \mu_{\text{max}} \) is the distance modulus corresponding to \( d_{\text{max}} \) and \( s \) is related to the distance modulus range over which the sample becomes incomplete. A suitable value of \( s \) was found empirically to be 3. This was achieved by fitting a sigmoid to the faint end of histograms of the numbers of objects of a given spectral type against apparent magnitude. By applying this weight, objects which lie well beyond \( d_{\text{max}} \), where the sample is not complete for all expected extinctions, are given approximately zero weight, whilst those well within \( d_{\text{max}} \) are given a weight of almost one.

A Bayesian classification method is employed to estimate the luminosity class into which each object falls, given the determined distance–extinction relationship, the apparent magnitude of the object, an estimate of the extinction to the object and an estimate of its intrinsic colour. The luminosity class sequences are assumed to have Gaussian spread in absolute magnitude, with all sequences having equal and constant spread. The classification is made by evaluating the posterior probability that an object belongs to a luminosity class, given its extinction, the distance–extinction relationship and the absolute magnitude of that class. The choice of the prior used is discussed in Section 4.3.

A threshold probability is imposed, such that when the probabilities of all five classes fall below this, the object is removed from consideration in that iteration. This removes objects which do not appear to fit into any of the luminosity classes.

These procedures are put into an iterative structure, as shown in Fig. 9. The sense of the iteration can be summarized as follows: the distance, extinction and intrinsic colour of each object is estimated; then these determinations are binned to get a distance–extinction relation; this is then used to determine the luminosity class of the objects; and then the distance, extinction and intrinsic colour are estimated again, given the new estimate of luminosity class. The process has shown good convergence in all cases examined so far. In the range of 5–10 iterations are normally required. Convergence is discussed further in Section 4.2.

MEAD begins with the derivation of the distance–extinction relation defined by the early-A stars alone, that lies along the lower edge of the main stellar locus in the colour–colour plane. This is used to obtain the first estimate of the luminosity classes of all objects in the field. It is safe to assume that the great majority of objects on this strip are near main sequence, given that early-A giants are not only relatively rare but also exhibit slightly weaker 
\( H\alpha \) absorption that lifts them to higher \( (r' - H\alpha) \). This breaks the degeneracy between the different luminosity classes and enables distances to be reliably estimated at the outset (Drew et al. 2008).

When binning the data by distance MEAD ensures that: the depth of the bin is at least 100 pc; there are at least eight objects in the bin; the total signal-to-noise ratio in the bin is at least 130.

It should be noted that not all available data in the IPHAS data base are used in this algorithm. Only data flagged as either stellar or probably stellar in all three bands by the processing pipeline are accepted, with the remainder discarded straight away (for more details of the data processing see Irwin & Lewis 2001; Drew et al. 2005; González-Solares et al. 2008). As noted already in this section only a restricted stellar intrinsic colour range is exploited (marked in Figs 2 and 3): this is due in part to the Houk et al. (1997) calibration ending at K4V and also to the difficulties associated with modelling the molecular bands in late-type stars (Section 2). Following Drew et al. (2008), a maximum bright limit of \( r' = 13.5, i' = 11.5 \) and \( H\alpha = 12.5 \) is employed to avoid objects that may be saturated in one or more bands. Occasionally when any fainter objects are classified as saturated by the pipeline, the limit will be moved to the apparent magnitude of that object.

3.3 Possible contaminants

MEAD assumes that all the objects examined can be described by one of the luminosity class sequences. In practice there are a minority of exotic objects that will not fit into them. Generally such objects are not a problem if they neither have colours which are outside the range MEAD looks at or are significantly less frequent than normal objects. The latter argument relies on the statistical nature of MEAD. Although the properties of individual objects may be incorrectly estimated, the intention is that MEAD will derive the correct extinction–distance relationship given a large enough sample.

As previously mentioned, O and B stars are contaminant objects that may be mistaken for A and F stars. Fortunately, O and B stars are relatively rare, and present only in young populations. In populations older than \( \sim 100 \) Myr they are essentially absent. So, in large samples, with a mix of ages, we can comfortably assume field A and F stars dominate. The circumstance in which this assumption may come undone is in regions of ongoing star formation, especially if the stars that will become A and later-type MS stars are still in the pre-main-sequence (PMS) phase. If such objects remain in the minority for their locale, MEAD should recognize their raised luminosity and classify accordingly. If they become the dominant population, then MEAD may misinterpret them. In Section 5.3
MEAD is tested against IPHAS observations of the Cygnus OB2 association, where such extreme conditions could exist.

The subdwarf sequence occupies a very similar position on the IPHAS colour–colour plane as its dwarf equivalent and as such there is the possibility that subdwarfs may be erroneously identified as dwarfs and used in MEAD. However, in a volume limited sample it is expected that roughly one in every $10^7$ objects would be a subdwarf (Reid, Sahu & Hawley 2001). Given the faint absolute magnitudes of subdwarfs relative to the dwarfs, this proportion becomes even lower in the magnitude limited IPHAS catalogue. Furthermore, the imposition of a threshold probability in the Bayesian luminosity classifier will prompt MEAD to discard a large proportion of them as they are offset below the main sequence in colour–magnitude space.

Hydrogen atmosphere white dwarfs largely lie outside the main stellar locus, leaving only a minority inside the region of the colour–colour plane searched by MEAD: these objects will be the very coolest and the very hottest white dwarfs. White dwarfs exhibit absolute magnitudes approximately in the range $10 \lesssim r' \lesssim 15$. Given this and the IPHAS magnitude limits, the data base cannot contain even unreddened white dwarfs more distant than 1 kpc. It is estimated that there will be 7.6 white dwarfs per square degree in the IPHAS sample, representing ~0.01 per cent of all sources. This estimate is based on a detailed model of the Galactic population of white dwarfs (Napiwotzki 2008) calibrated using the observed white dwarf samples of Holberg et al. (2008) and Pauli et al. (2006), reddening is included in an approximate way. Many white dwarfs will be ignored by MEAD due to their colours lying outside the main stellar locus. Of the handful remaining within more will be discarded by the Bayesian luminosity classifier as belonging to a faint sequence.

Extragalactic sources will also contaminate the catalogue. Resolved galaxies will be flagged by the CASU pipeline as being extended objects and will be ignored by MEAD. In addition, even some small galaxy images will overlap with the very numerous stellar images and hence be classified as extended, also removing them from consideration. Nevertheless, some galaxy images will be sufficiently compact to be classified as stellar. Genuinely compact (i.e. physically small) galaxies are rare, contributing about 3 per cent of all low-redshift field galaxies down to $B \simeq 20$ ($r' \sim 19.5$) given similar seeing. From IPHAS field 2311o and simulated data (black), given similar seeing.

4 TESTING MEAD AGAINST SIMULATED PHOTOMETRY

The reliability and precision of MEAD needs to be appraised, by testing its performance on sightlines where the distance–extinction relation is exactly known. As there are no such ideal sightlines, it is necessary to synthesize model sightlines resembling those encountered in the Galactic disc, to which photometric errors can be applied that are consistent with IPHAS data. We do this by using Monte Carlo sampling techniques. These simulations also allow us to directly investigate the impact of factors such as metallicity on the performance of MEAD, in a way that would otherwise not be possible.

The simulations were created largely following the Besançon galaxy model. The initial mass function (IMF) of Kroupa (2001) and the Galactic extinction model of Amâres & Lépine (2005) were assumed. The simulations were populated with objects from a copy of the Teramo library of isochrones and stellar evolutionary tracks (Pietrinferni et al. 2004). These were translated into the IPHAS filter system using the finely sampled grid of model SEDs due to Munari et al. (2005). Photometric errors were imposed, adopting random errors based on the CCD equation (see Fig. 10) along with field wide systematic errors of the order of 1.5 per cent, arising from the calculation of the aperture correction and photometric zero-points.

4.1 Comparisons between simulations and real data

Although it would be possible to create an end to end simulation, whereby synthetic images are created and then pipelined in the same manner as IPHAS observations, this would be so excessively time consuming as to restrict the analysis of MEAD’s performance. Instead, the simpler method used here begins with the application of MEAD to the synthesized magnitudes. This allows the production
Extinction mapping with IPHAS

4.2 The basic performance of MEAD

With the photometric errors, metallicity variation and binary fraction set to zero, MEAD is very successful at retrieving the input distance–extinction relation, as shown in Fig. 12. The little spread on extinction that does exist is a result of describing the continuous stellar evolutionary tracks in terms of five discrete luminosity classes (see Fig. 2). In this manner we can see that the errors introduced by this description are small ($\delta A_r \sim 0.05$) and so this is a valid method.

To be credible, the solution must converge. Although MEAD will exit when complete convergence has been reached it is unreasonable to wait for every last small change to be made, especially if the last corrections to a few stars become oscillatory. Fig. 13 demonstrates the convergence rate for one execution of MEAD, whilst Fig. 14 characterizes the convergence rate for a large number of visualizations. The default maximum number of iterations for MEAD is set to 15.

4.3 Calibration of priors for the determination of luminosity class

In Section 3 it was noted that it was possible to include a non-uniform prior probability when determining the luminosity class of a given object. Using the simulated photometry the probability distribution for the prior which retrieves the most accurate result was determined from a representative sample of sightlines. The

Figure 11. A comparison between observed (left-hand panels) and simulated (right-hand panels), colour–colour (top) and colour–magnitude (bottom) diagrams, given similar conditions, in the direction $(l, b) = (170, 0)$. The observed data are the observations of IPHAS field 2311o and include only objects classified as stellar or probably stellar. A magnitude cut at $r' = 20$ has been applied to both the observed and real data. The differences between the two sets of data are due to: differences between the real and model distance–extinction relationship; differences between the distributions of objects with respect to distance; and some types of objects not being included in the simulations.

Figure 12. The determined points on the extinction–distance relationship from 25 simulations (black) and the underlying extinction, input to the simulations (red).
accuracy is defined in terms of minimizing the $\chi^2$ statistic:

$$\chi^2 = \sum_i \frac{(A_{\text{est}} - A_{\text{act}})^2}{\sigma_i^2 + \delta A_i^2},$$

where $A_{\text{act}}$ is the extinction estimated by MEAD and $A_{\text{act}}$ the extinction from the model at the same distance. In the denominator, $\sigma_i$ is the intrinsic standard deviation of extinction in the distance bin (i.e. due to the porosity of the ISM), while $\delta A_i$ is the error in $A_{\text{act}}$ as a consequence of the photometric errors.

Given that simulating sufficient sightlines is relatively time consuming, it was not possible to search the entire parameter space, whilst the uncertain structure of the parameter space made ‘downhill-only’ root finding algorithms inadvisable. Therefore, a simulated annealing algorithm was used to minimize the statistic above. It was found that the prior should take the following form, where $P(X)$ is the probability assigned to luminosity class $X$: $P(V) = 0.34; P(IV) = 0.31; P(III) = 0.28; P(II) = 0.06; P(I) = 0.01$. This prior mirrors the number of objects in each class in the simulated photometry. As the IPHAS bright magnitude limit is at $r' \sim 13.5$, neither bright giants ($M_r \lesssim -2$) nor supergiants ($M_r \lesssim -6.5$) are likely to be present in large numbers.

We note that this set of priors has been derived from a weighting of sightlines that, at the present time, emphasizes the moderately reddened directions in the Galactic plane encountered at all latitudes outside the solar circle, and at latitudes $|b| > 1$ within it. This set was specifically chosen to correspond to those sightlines investigated in this paper. For these sightlines dwarfs are strongly dominant and so the results show little sensitivity to the choice of priors. The priors for the highest reddening sightlines passing into the inner Galaxy are under investigation. It may prove necessary to attribute somewhat increased probabilities to brighter luminosity classes.

### 4.4 Coping with unresolved substructure and photometric errors

In MEAD, once estimates of distance and extinction are produced for each object, the data are binned, with respect to distance, to produce a distance–extinction relationship. As discussed in Section 3, the extinction will not be uniform for a finite-sized box at any given distance. Instead it will vary with sky angle, just as it will vary with depth, due to unresolved substructure prompting some intrinsic variation in extinction. Hence, in this study, the extinction in any given bin is characterized as having some intrinsic scatter.

If the photometric errors are propagated through to give the error on the determined value of the extinction, it is possible to determine maximum likelihood estimators (MLEs) for the mean and intrinsic standard deviation of the extinction, if the character of the variation in extinction is known. If the variation of extinction is Gaussian, then the estimate of the mean value of the extinction in each bin (A) is given by the following equation:

$$A = \frac{\sum A_i + \delta A_i^2}{\sum 1/(\sigma_i^2 + \delta A_i^2)},$$

where $A_i$ is the estimated extinction for a single object, and other terms are as described in Section 4.3:

This estimate is essentially a weighted mean of the individual estimates of extinctions for each object in the bin. It is found that the intrinsic scatter of extinction in each bin ($\sigma_i$) can be satisfactorily estimated by the weighted standard deviation of the extinctions of the brighter objects in the bin (those with $dA_{6250} \leq 0.1$). The weighting for this estimate is the weight given by equation (3) over $dA_{6250}$.

In reality, the intrinsic scatter of extinction in each distance bin is a result of the turbulent processes at work in the ISM. If the extinction of each simulated object is scattered away from the mean value for the distance as a result of Kolmogorov turbulence, MEAD still successfully retrieves the input extinction, despite the in-built assumption that extinction at a given distance is scattered normally (Fig. 15).
4.5 Handling of magnitude limits

In Section 3.2 we discuss the difficulties associated with the magnitude limits and how these have affected previous extinction maps. The treatment for this problem involves ignoring data which are at a distance where they could be affected by incompleteness. The parameter $n$ in equations (1) and (2) determines which data are ignored, but there is no obvious value it should take. To establish the ideal value of $n$, MEAD was tested against variation of this parameter. Setting the value of $n$ too low allows the inclusion of objects which may bias the results, due to the effect of incompleteness becoming increasingly relevant. It was found that for $n < 2$ the results of MEAD would be unsatisfactory, an example of this effect is shown in Fig. 16. Raising $n$ acts to reduce the number of objects which can be used to determine the distance–extinction relationship, thus decreasing the range and distance resolution of the outcome. Although many of the objects filtered out should be removed for reasons of incompleteness, others need not be and are lost undeservedly. A compromise is necessary. We set $n = 2$ so as to use the maximum possible number of objects whilst avoiding the magnitude limit effect. Fig. 17 illustrates that setting $n = 2$ obtains the highest number of accurate distance bins on the derived distance–extinction relationship whilst maintaining a low proportion of bad bins.

4.6 Achievable angular resolution

Previous observational 3D extinction maps of the Milky Way (Fitzgerald 1968; Lucke 1978; Neckel et al. 1980; Pandey & Mahra 1987; Joshi 2005, e.g.) have been carried out at angular resolutions of the order of a few degrees. The recent extinction map due to Marshall et al. (2006) has a resolution of 30 arcmin. With the high angular density of sources in the IPHAS data base ($\sim 10^5 \text{deg}^{-2}$) it is clearly possible to map extinction at a much finer angular resolution. The resolutions possible are dependent on the source density, but even in the relatively sparsely populated galactic anticentre resolutions of 10 arcmin are achievable.

4.7 Bias in distance estimation

The estimate of the distance modulus to each object has a symmetric error distribution around its mean. However, the expected distribution of stars is not symmetric as the volume of space in which a star lies and the density of stars changes. Therefore, the expectation of the true distance to the star does not equal the original estimate and so that original estimate is biased. An analogous effect leads to the well-known Lutz–Kelker bias (Lutz & Kelker 1973), when using trigonometric parallaxes to estimate the absolute magnitudes of objects. Following Lutz & Kelker (1973) it is possible to derive a correction for this bias, if the density of stars is assumed to be uniform. If this correction is applied to the distance bins of objects from the simulated photometry, where the stellar density is assumed to be uniform, the median correction is found to be 0.1 per cent, whilst 95 per cent of bins have corrections less than 1 per cent. The improvement on the agreement between the input and derived extinction–distance relationships is thus negligible.

Calculating a correction for a realistic density distribution is considerably more difficult. However, the median correction will often be smaller than in the case of uniform stellar density, because of the drop off in stellar density associated with most sightlines.

4.8 Sensitivity to disc metallicity gradients

The Besançon model assumes a smooth gradient in the mean metallicity with respect to galactocentric radius ($R_G$). This view is shared by Friel et al. (2002) and Bragaglia & Tosi (2006) amongst others. However, it has been argued (e.g. Twarog, Ashman & Anthony-Twarog 1997; Corder & Twarog 2001; Yong, Carney & Teixera de Almeida 2005) that metallicity in fact varies as a step function of $R_G$, with the step occurring at $R_G \sim 10$ kpc. Carraro et al. (2007) and Bragaglia et al. (2008) argue that any gradient flattens to a constant metallicity in the outer disc. Given this spread in opinion it was necessary to test the performance of MEAD against a range of different schemes.

It was previously shown in Fig. 4 that metallicity has almost no effect on the colours of A0–K4 stars. The absolute magnitudes, on the other hand, are metallicity dependent, but these do not become significant until metallicities are markedly subsolar (Fig. 5).
Consistent with this we find that introducing metallicity variations induces little change in the output from MEAD, even though MEAD assumes solar metallicity. This is true of all the above mentioned schemes for the disc metallicity gradient.

4.9 Correction for binarity

Unresolved binaries and higher multiples present the possibility of the systematic overestimation of point source absolute magnitudes. For the objects selected by MEAD (A0–K4), the effect of binarity on the observed colours is small (Hurley & Tout 1998).

In the extreme case of binaries of unit mass ratio the distance to an object would be underestimated by a factor of \( \sqrt{2} \) compared to the single-star case. However, on making plausible allowances for the binary mass ratio distribution and for the binary fraction, it is likely that, in the mean, distances will only be underestimated by a factor of a few per cent. For example, the expected underestimate of distance will be \( \sim 5 \) per cent if the Kroupa (2001) IMF, Duquennoy & Mayor (1991) binary fraction, a constant probability function for binary mass ratio and a mass–luminosity relation of \( L \propto M^{3.5} \) are all assumed.

To arrive at a correction factor that may be applied routinely within MEAD, the effect of binarity has been analysed through the use of simulated photometry. Binaries were inserted in the model using a binary fraction of 57 per cent, following Duquennoy & Mayor (1991) which is derived from observations of G type stars. Lada (2006) demonstrates that the binary fraction drops significantly for later type stars, but these are mostly those which are not simulated (i.e. M type stars and later). The probability function for the binary mass ratio was assumed to be constant, whilst higher order unresolved multiples are assumed to be relatively rare (Duquennoy & Mayor 1991) and so are not included in the simulation.

The outcome of this exercise is that there is systematic underestimation of distances, which in turn causes extinction to be overestimated in a given distance bin. The appropriate correction for this is made by multiplying all the derived distances by 1.06. This figure was derived through minimization of the statistic in equation (4), over 100 visualizations of six different sightlines. This modification should function successfully as most bins contain relatively large numbers of objects and the correction itself is small. When this correction is adopted MEAD successfully reproduces the input distance–extinction relationship.

4.10 Impact of reddening law variations

MEAD and the simulations performed up until this point assume the \( R = 3.1 \) reddening law of Fitzpatrick (2004). To investigate the effect of altering \( R \) significantly, simulated photometry was created with \( R = 2.6 \) and 3.6 reddening laws. Then MEAD was run on the results of these simulations, while continuing to apply the \( R = 3.1 \) law. Fig. 18 shows that the impact on MEAD’s mapping of sightlines better represented by non-standard reddening laws is to induce a systematic error that is comparable – in these examples – with the typical random error. Had the reddening been expressed in terms of the monochromatic extinction, \( A_{V} \), Fig. 18 would look much the same. However, a conversion into \( A_{V} \) would be even more dependent on the value of \( R \) and therefore the outcome of a mapping expressed in terms of \( A_{V} \) would be subject to even greater systematic error. The sense of the bias is that the extinction at a given distance for sightlines of anomalously high \( R \) is underestimated.

Given that IPHAS observations provide magnitudes in just three bands, it is not feasible to constrain \( R \) in addition to the intrinsic colour, extinction and luminosity class (and so distance). Instead it is preferable to rely on the relative dominance of the \( R = 3.1 \) reddening law across the Galactic plane. The same assumption has been made previously by Neckel et al. (1980); Schlegel et al. (1998); Marshall et al. (2006) and many others. If the IPHAS data base were to be cross-matched with the results of the United Kingdom Infrared Deep Sky Survey Galactic Plane Survey (UKIDSS GPS; Lucas et al. 2008) and the Ultraviolet Excess Survey of the northern Galactic plane (UVEX; Groot et al., in preparation) the extra measurements would facilitate the accurate estimation of \( R \), whilst still maintaining the accuracy of the other estimates.

4.11 The impact of very young populations

O, B and very early A stars occupy the same area of the IPHAS colour–colour plane as less extinguished later A and F stars. However, they also respond differently to extinction and have different absolute magnitudes and so introduce a degeneracy into the problem. In the interarm field such objects are comparatively rare, with their short lifespans and the IMF suppressing their frequency. However, in the spiral arms such objects are more frequent, due to the ongoing star formation induced by the passage of the spiral density wave. The Besançon model makes no allowance for spiral-arm-induced star formation, since a constant star formation rate is adopted for all locations. Therefore simulations based on the Galactic model cannot provide any insight into the impact of these localized young populations. We have carried out some tests of such concentrations by inserting them into model sightlines in order to mimic the superposition of a spiral arm. The results show no additional systematic error in the derived extinction curves that would imply a breakdown of the method.

As with early-type stars, PMS objects introduce degeneracy due to their different colours, absolute magnitudes and response to extinction as compared to the sequences assumed in the calibration of MEAD. Also, as with early-type stars, PMS objects would normally be found concentrated in star-forming regions. So as to investigate the effect of including PMS objects the extra spiral arm population was again included in the model. The inserted PMS objects were then tracked through MEAD. In reality, many PMS objects exhibit H\( \alpha \) emission and so lie outside the main stellar locus on colour–colour plots and are thus ignored by MEAD. However, those PMS objects exhibiting weaker H\( \alpha \) emission would
remain inside the main stellar locus, where they may be misidentified by MEAD. As with O and B stars, the relative scarcity of emission-line PMS stars compared to normal stars should limit this problem. As a direct test of this and other expectations regarding young populations, we present and discuss the example of sightlines through Cyg OB2, a spectacular northern OB association, in Section 5.3.

4.12 The impact of photometric zero-point errors

At the time of writing the IPHAS data base lacks a global calibration, with observations instead being calibrated on a run-by-run basis, with the Hα calibration tied to the r′ calibration. As such it is possible that there will be offsets between the true and measured magnitudes in one or more bands. To investigate the effects of such difficulties, offsets were manually introduced into the simulated photometry.

The effect of adding the same magnitude offset to all three bands is simple to understand, as this will simply lead to inaccurate determinations of the distance to each object. For example, an offset of 0.10 mag is well within the range of what might be encountered within the IPHAS data base presently. This offset leads to a 5 per cent error in determined distances.

Somewhat less straightforward is the effect of offsetting one band only, as this will affect the intrinsic colours and extinctions determined for each object, and so the object distance as well. Fig. 19 shows the effect of applying a positive and negative offset to Hα. There are two consequences of doing this. The first is that the accuracy of MEAD is reduced, as all objects are now systematically misidentified. This effect can be seen clearly by comparing the two panels in Fig. 19. Secondly, MEAD returns fewer points, for the case of a negative offset to Hα. This can be very serious as it may reduce the number of returned points significantly. In the case shown 90 per cent of the objects available are lost: this is because the main stellar locus has shifted largely outside the region of the colour–colour diagram searched by MEAD.

Figure 19. The top panel shows the retrieved extinction–distance relationship, given an offset of 0.05 (black dots) or −0.05 (green crosses) to the Hα magnitudes of the objects. The bottom panel shows the results with no offset (black dots). On both panels the input relationship is shown as the red line. The simulations are for the direction (l, b) = (180, 0).

Figure 20. Distance–extinction relationship for field 4199 in the direction (l, b) = (32.0, 2.0), using a 10 × 10-arcmin² box. The relationship derived in this paper is in black, with the error bars indicated the errors on the derived mean value of extinction in each bin. The result of Neckel et al. (1980) is in green, the Schlegel et al. (1998) asymptotic value is shown with the blue dashed line, the Drimmel & Spergel (2001) model in cyan and the Marshall et al. (2006) results are shown with red crosses. Estimates of extinction and distance for 1197 objects have been binned up to produce the distance–extinction relationship.

Until a global photometric calibration is performed, tying the Hα calibration to r′ vastly reduces the frequency and size of offsets in the (r′ − Hα). In the future the calibration in the i′ band will also be tied to the r′-band calibration, improving the suitability of the data for use in MEAD.

5 EXAMPLE APPLICATIONS OF MEAD

5.1 A sightline in Aquila, through (l, b = 32.0, 2.0)

For this direction, the results from this paper (Fig. 20) show two significant increases of extinction, one within the first few hundred parsecs, which would be associated with the Aquila Rift. The Rift is at a distance of ~200 pc (Dame et al. 1987), with the extinction rising to A_v ~ 3(A_r ~ 2.5) (Stańczyk, Cernis & Bartašiūtė 2003). We find that the extinction through the Rift is somewhat higher, reaching A_v ~ 4.7 (or A_r ~ 4) at this position. The second extinction rise lies at ~2 kpc and is likely to be associated with the Sagittarius Arm. The extinction then asymptotes beyond it at a value roughly consistent with the Schlegel et al. (1998) limit for this direction.

Previous extinction–distance relations for this sightline are also shown in Fig. 20. At distances greater than 2 kpc, MEAD produces a relation that is quite similar to that of Marshall et al. (2006). It is clear, however, that the Marshall et al. (2006) modelling does not take into account the more local Aquila Rift. It is this difference, in particular, that lies behind the great discrepancy between their first data point at ~2 kpc and our relation. At all distances we find the extinction to be markedly higher than given by the relation due to Drimmel & Spergel (2001). These distinctions begin to illustrate the value of an approach that does not depend on Galactic models.

5.2 The sightline through the open cluster NGC 2099 (l, b = 177.6, 3.1)

The Galactic cluster, NGC 2099 (M37) lies near the anticentre at (l, b) = (177.6, 3.1). Hartman et al. (2008) measure this cluster to be at a distance of 1.49 ± 0.12 kpc with a reddening of E(B − V) = 0.23 ± 0.04. This sightline falls within IPHAS field 2849. The distance–extinction relationship derived in this paper and in the
literature, are shown in Figs 21 and 22. The difference between the two plots is that in the first the errors on the estimated value of extinction for each bin are marked (these arise from systematic and random errors involved in obtaining the photometry), while in the second, the error bars reflect the intrinsic scatter that is a consequence of the existence of unresolved substructure in the interstellar medium.

Both of these must be known to estimate the distance of an object based on its extinction and the distance–extinction relationship. Using the distance–extinction relationship shown above and the Hartman et al. (2008) estimate of reddening, the distance to NGC 2099 is estimated to be 2.0 ± 0.9 kpc, where the large error is a result of the extinction–distance relationship flattening off between ~2 and ~3 kpc. Based on the distance to W3OH of 1.95 ± 0.04 kpc (Xu et al. 2006), this void in extinction would appear to lie directly behind the Perseus spiral arm.

Nilakshi & Sagar (2002) measure a reddening of $E(B - V) = 0.30 \pm 0.04$ and a distance of 1.36 ± 0.1 kpc to NGC 2099, this estimate is a significantly poorer fit to derived distance–extinction relation than the estimate of Hartman et al. (2008). The cause of the difference between these two results appears to be the adopted metallicity: Hartman et al. (2008) adopt a nearly solar value, while Nilakshi & Sagar (2002) prefer a reduced metallicity of Z = 0.008. If all objects were assumed to have fainter absolute magnitudes, in line with the Nilakshi & Sagar (2002) metallicity, the distance and extinction determined by Hartman et al. (2008) remains a better fit to the produced distance–extinction relation.

5.3 Cygnus OB2

A potentially difficult environment for MEAD to operate in is one with substantial ongoing star formation (Section 4.11). In such regions there will be relatively large numbers of PMS objects which are not explicitly identified in the algorithm and therefore may be more subject to misclassification, and in addition any O and B stars present will be mistaken for A/F stars. One such region is the Cygnus OB2 association. Cyg OB2 has been extensively studied in the past, and in particular Drew et al. (2008) utilized IPHAS photometry to study the positions of early-A stars around the association, concluding that it lies at a distance between 1.45 and 1.75 kpc, with the range in distances a result of uncertainty in the age of the association.

IPHAS fields 5985 and 6010 look towards the approximate centre of the Cygnus OB2 association, having field centres at (l, b) = (80.3, 1.2) and (l, b) = (80.2, 0.7), respectively. Fig. 23 show the derived distance–extinction relationships for these fields: in both cases a substantial increase in extinction is apparent at ~1.5 kpc. This rise in extinction would therefore appear to be associated with Cygnus OB2 association. In field 5985 the extinction flattens out and approaches its asymptotic value. This flattening is not seen in the results for field 6010 – most likely due to the extinction continuing to rise significantly beyond Cyg OB2, placing most objects outside the magnitude limits of the observations. Schlegel et al. (1998) find significantly higher values of asymptotic extinction in field 6010 than in 5985, consistent with this (see also Drew et al. 2008).

The range over which the extinction sharply rises in field 5985 is ~400 pc. It is not likely that the extinction associated with the Cygnus OB2 association itself is this deep, but rather that the cumulative errors are inducing a smoothing of the distance–extinction relationship (a point commented on by Jurić et al. 2008). Using the Monte Carlo method for simulating photometry, it is possible to produce a result similar to the ones displayed in both fields with the extra extinction confined to a depth of $\lesssim$100 pc at a distance of (1.5 ± 0.2) kpc in the model.

A second method for determining the distance to the Cygnus OB2 association is to determine the ratio of the number of younger stars to a sample with longer lifetimes along the line of sight. Early A (A0–5) near MS stars were used as the younger population due to their...
relative ease of selection and the low probability of contamination by non-MS stars. Their number was compared with that of late F type dwarfs (F5–9), a population with an MS lifetimes roughly 10 times longer. Ideally a sample of redder dwarfs or giants would be preferred in this role, but later type dwarfs are too faint to be observed over a large enough distance range, due to the rapidly rising extinction, while giants are not sufficiently numerous in this region. Fig. 24 demonstrates the dependence of this ratio on distance within field 5985, showing a significant peak at 1.55 kpc. This distance is consistent with both that determined in Drew et al. (2008) and the rise in extinction shown in Fig. 23. The peak shown in Fig. 24 is not as broad as the region of high differential extinction in Fig. 23, this is a consequence of the near MS early-A stars being relatively bright and so exhibiting smaller photometric and therefore distance, errors.

As previously mentioned, a significant concern when analysing fields in Cyg OB2 is contamination by PMS objects. PMS objects will exhibit brighter absolute magnitudes than MS objects of the same intrinsic \((r' - i')\) colour and thus their distance would be underestimated if they were classified as dwarfs. Therefore it might be expected that distance bins closer than Cyg OB2 might incorrectly contain objects with higher extinctions, thus causing the estimate of mean extinction in these bins to be too high. However, many PMS objects will actually be classified in luminosity classes IV or III, especially if they have blue intrinsic colours where the luminosity classes are tightly spaced (Fig. 2). The ability to classify these objects in classes IV or III will result in a more accurate estimation of distance. But it must be acknowledged that there is room for some falsification through application of absolute magnitude scales derived for evolved stars. A second, potentially more serious, problem is a result of the behaviour of PMS objects on the colour–colour diagram, particularly in relation to the Hα band. Although substantial Hα line emission will move an object outside the main stellar locus, less pronounced emission could result in an object still lying within the main stellar locus and MEAD estimating an intrinsic colour redder than reality and too low a value of extinction.

Field 6134 \([(l, b) = (81.46, -0.72)]\) is outside Cyg OB2, but due to its relative proximity should exhibit similar properties to fields 5985 and 6010 at distances less than that to Cyg OB2. Fig 23 demonstrates that the local \((<1 \text{ kpc})\) behaviour of extinction in fields 5985, 6010 and 6134 is much the same. This is as it should be, since at these near distances the field centres are less than 50 pc apart and likely to be sampling much the same stellar environment. Further examination of the results for field 5985 reveals a 30 per cent increase in the proportion of objects in luminosity classes IV and III, relative to field 6134, suggesting that MEAD is indeed capable of dealing with the brighter absolute magnitudes of PMS objects.

6 DISCUSSION

We have presented an algorithm, MEAD, and shown how it can be applied to the \(r', i'\) and narrow-band Hα photometry forming the IPHAS data base to map out extinction in the Galactic disc at high angular and depth resolution. The algorithm is fully empirical in that it depends only on absolute magnitude calibrations (especially the Houk et al. 1997 Hipparcos main sequence) and not on any Galactic model. Because of this it is better able to deal with perturbations away from a smooth structure. This is crucial as it is these perturbations which are of real interest, in view of their possible origin due to either accreted satellite galaxies or to the Milky Way’s still-debated spiral structure.

Jurić et al. (2008) are able to successfully correct for extinction using the 2D maps due to Schlegel et al. (1998), since the majority of their observations sample high Galactic latitudes. For studies of the Galactic disc at low latitudes, a more sophisticated treatment of extinction is required. The algorithm MEAD presented here is a means to achieving this. While the Jurić et al. (2008) SDSS sample is effectively volume limited for most spectral types, leading to MS stars dominating the sample, the IPHAS data base is more clearly magnitude limited, requiring the disentangling of luminosity class. This capability is a critical new feature of MEAD.

The new power of MEAD can be illustrated by comparing the distance–extinction relationships obtained (i) using A stars only (as in Drew et al. 2008), (ii) analysing intrinsic colour, whilst classifying all stars as dwarfs, (iii) using MEAD in full (Fig. 25). Drew et al. (2008) demonstrated that extinctions and distances of near MS early-A stars were particularly straightforward to derive from their IPHAS colours and apparent magnitude. This approach, on its own, could in principle be used to map extinction, but near MS early-A stars represent only a small proportion of objects in the IPHAS catalogue. By accessing a broader range of intrinsic stellar colours MEAD is able to map extinctions on finer spatial scales, with greater accuracy and over a wider distance range. This figure also demonstrates why it is so important to analyse luminosity class as well as intrinsic colour.

As well as estimating the distance–extinction relation, MEAD also returns distance, intrinsic colour and extinction estimates for a large proportion of objects in the IPHAS data base. Interpreting the resultant catalogue, will be non-trivial, but will enable the structure of the Galactic plane to be studied in a manner similar to the analysis.
of the Milky Way at higher latitudes by Jurić et al. (2008). For example, scaleheights and scalelengths of both the dust and stars within the disc will be derivable.

A side benefit of MEAD is that it generates lists of objects that do not conform to the most common spectral classifications. These ‘rejected’ objects may still be of interest for focused studies of rare phases of stellar evolution. Whilst, most of the objects in this category will be late K or M type stars, or noise dominated, others would be extreme red giants (Wright et al. 2008), subluminous objects (Section 3.3) or emission line stars. Witham et al. (2008) have already presented a preliminary catalogue of emission line stars extracted from above the main stellar locus.

In the future, MEAD could also be applied to the results of the upcoming VST/OMEGACAM Photometric Hydrogen Alpha Survey of the southern Galactic plane (VPHAS+). Combining the results from VPHAS+ and IPHAS would lead to an extinction map of the entire Galactic plane in unprecedented detail. VPHAS+ and UVEX extend the wavelength coverage of IPHAS to the u' and g' bands over the full plane. These additional bands open up the investigation of variations in metallicity (cf. Ivezic et al. 2008) and in the extinction law. Here, in limiting ourselves to red wavelengths, we have been able to work with a standard $R = 3.1$ law as reasonably representative of most sightlines. Combination with near-infrared wavelengths is also becoming an option as the UKIDSS GPS progresses and VISTA (Visible and Infrared Survey Telescope for Astronomy) begins data collection.

As a next step, the impending completion of IPHAS observing creates the opportunity to apply MEAD to a full 3D mapping of the northern Galactic plane (Sale et al., in preparation).

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