UPPAAL 4.0

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Abstract—UPPAAL 4.0 is the result of over two and a half years of development and contains many new features, additions to the modeling language, performance improvements, enhancements and polish to the the easy to use graphical user interface, and is accompanied by several open source libraries. The tool and libraries are available free of charge for academic, educational and evaluation purposes from http://www.uppaal.com. We describe three of the new features: User defined functions, priorities and symmetry reduction.

I. INTRODUCTION

UPPAAL is a verification tool for timed automata. Its focus on speed and usability has made the tool popular both as a teaching tool in academia, as a gentle introduction to the world of model checking, and as a tool for doing serious case studies as witnessed by the large number of publications in which UPPAAL was used. Version 4.0 was released in May 2006 and introduces many new features that increase the applicability and the performance of the tool. This paper describes three major features of the new release. Many more are worth describing (such as a typical reduction in memory usage of a factor 3 to 5, new abstraction techniques resulting in large performance increases [1], or our implementation of the generalised sweep line method), however lack of space forces us to focus on the most visible changes.

II. USER DEFINED FUNCTIONS

Many problems require non-trivial computations with complex control-flow to be embedded in the model. In a graphical language like the one used by UPPAAL, this tends to clutter the model and makes the model hard to read and maintain. Often, including such computations in the model enlarges the state space by introducing intermediate states and irrelevant interleaving. In the past, this has led to the addition of committed locations in UPPAAL to build atomic sequences.

In UPPAAL 4.0 we have extended the modeling language with user defined functions. These are fully integrated into the modeling language, and have access and can modify all state variables. The syntax follows the style of C/C++/Java, and most control-flow constructs of C are supported. Functions are evaluated atomically and must be deterministic, whereby intermediate states are avoided (similar to the d_step construction in SPIN, which marks a sequence of statements as atomic and deterministic). The only limitations are that recursive calls are not allowed and functions must eventually return. The second requirement is currently not enforced by UPPAAL, and UPPAAL will not terminate if a user defined function enters an infinite loop (this is a technicality and the language was designed such that future versions of UPPAAL can be extended to analyze the model for such problems).

User defined functions are compiled to byte-code, and executed at verification time on a small embedded stack machine. We have decided not to use an external compiler like gcc, even though this would result in faster evaluation of complicated functions. The dependence on an external compiler would complicate the installation procedure of UPPAAL considerably. We do not expect the virtual machine to be a bottleneck for verification, as most time is spent on other operations anyway.

The extension has proven to be extremely useful in almost all UPPAAL models. Typical uses include that of naming or hiding complicated expressions from the graphical language, performing updates on data structures like routing tables, queues, and stacks (although, the size of such data structures must always be bounded), and performing computations that require loops and complex control-flow. One of the more ingenious uses we have seen, is to implement an interpreter for live sequence charts, which when embedded in a UPPAAL model can be used to check conformance.

III. PRIORITIES

In the implementation of real-time systems, the priorities are often associated with processes (or tasks) to structure and control the usage of shared resources such as CPU or shared memory. As a consequence, programming languages and scheduling policies used in real-time operating systems are often based on a notion of priorities on tasks. In lower levels, priorities are often associated with interrupts to hardware devices and access to e.g., shared communication buses.

In UPPAAL 4.0 we have extended the modelling language with priorities on channels and automata [2]. The priority orders defined in the model are translated into a priority order on internal and synchronizing transitions. At a given time-point, an enabled transition will block (disable) another if it has a higher priority.

The example below specifies that channel a has a lower priority than channels b and c, and that the automaton P has...
with priorities on both automata and channels, we resolve priorities by comparing priorities on channels first. If they are the same, the automata priorities are compared. For efficient model-checking the priority orders are total orders.

\texttt{chan priority a < b, c; system P < Q, R;}

\textit{UPPAAL} uses difference bound matrices (DBMs) \cite{4} to represent convex constraints on clock variables. The efficient implementation of priorities is made possible by the introduction of a optimised subtraction operation in the DBM library. However, the result of the subtraction is not necessarily a convex zone, but rather a set of zones. The algorithm we use for subtraction generates a disjoint set of DBMs, and uses a heuristic to minimise the number of DBMs in the result. The library even supports merging zones back together.

\section*{IV. Symmetry Reduction}

Symmetry reduction is a well-known technique to alleviate the state-space explosion problem and has recently been added to \textit{UPPAAL}. This technique can be applied to models that contain multiple equivalently behaving processes \cite{4}. Consider, for instance, Fischer’s mutual exclusion algorithm. It consists of a set of processes that only differ in their “identity”. A process writes its identity in a global variable and checks after for instance, Fischer’s mutual exclusion algorithm. It consists

\texttt{of multiple equivalently behaving processes \cite{4}. Consider,}

\texttt{for instance, Fischer’s mutex algorithm. It consists of such algorithms often consist of a number of symmetric processes. For instance, symmetry reduction in \textit{UPPAAL} has been successfully applied to the leader election algorithm in \cite{5}, a consensus algorithm \cite{6} and the Zeroconf protocol \cite{7}.}

\footnote{The work in \cite{6} does not use automatic symmetry reduction, but recent experiments show that this can be done with a significant gain.}

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\textbf{process writes its identity in a global variable and checks after} & \texttt{for instance, Fischer’s mutual exclusion algorithm. It consists} & \texttt{of multiple equivalently behaving processes \cite{4}. Consider,} \\
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We have described three of the most visible new features of \textit{UPPAAL} 4.0. The DBM library is released under the GPL and contains language bindings for C, C++ and Ruby. The parser library is released under the LGPL and is ideal for implementing model transformation tools or analysis tools. Java parsers and client stubs for the verification backend are distributed with \textit{UPPAAL} and may be used by, e.g., domain specific tools (the documentation can be found at our web site). Finally, \textit{UPPAAL} can be used as a compiler for \textit{UPPAAL} models, translating the model to a byte-code representation.

\section*{ACKNOWLEDGMENT}

The authors thank Kim Algreen, Marius Mikucionis, Leonid Mokrushin, Ulrik Nyman, Robert Olesen, and Jacob Illum Rasmussen for their contributions to \textit{UPPAAL} 4.0.

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