On the sensitivity of gravito-inertial modes to differential rotation in intermediate-mass main-sequence stars

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ABSTRACT

Context. While rotation has a major impact on stellar structure and evolution, its effects are not well understood. Thanks to high-quality and long timebase photometric observations obtained with recent space missions, we are now able to study stellar rotation more precisely.

Aims. We aim to constrain radial differential rotation profiles in \( \gamma \) Doradus (\( \gamma \) Dor) stars, and to develop new theoretical seismic diagnosis for such stars with rapid and potentially non-uniform rotation.

Methods. We derive a new asymptotic description which accounts for the impact of weak differential near-core rotation on gravity-mode period spacings. The theoretical predictions are illustrated from pulsation computations with the code GYRE and compared with observations of \( \gamma \) Dor stars. When possible, we also derive the surface rotation rates in these stars by detecting and analysing signatures of rotational modulation, and compute the core-to-surface rotation ratios.

Results. Stellar rotation has to be strongly differential before its effects on period spacing patterns can be detected, unless multiple period spacing patterns can be compared. Six stars in our sample exhibit a single unexplained period spacing pattern of retrograde modes. We hypothesise that these are Yanai modes. Finally, we find signatures of rotational spot modulation in the photometric data of eight targets.

Conclusions. If only one period spacing pattern is detected and analysed for a star, it is difficult to detect differential rotation. A rigidly rotating model will often provide the best solution. Differential rotation can only be detected when multiple period spacing patterns have been found for a single star or its surface rotation rate is known as well. This is the case for eight stars in our sample, revealing surface-to-core rotation ratios between 0.95 and 1.05.

Key words. asteroseismology - methods: data analysis - stars: fundamental parameters - stars: variables: general - stars: oscillations (including pulsations) - stars: rotation

1. Introduction

Rotation is a crucial element of stellar structure and evolution (e.g., Maeder\textsuperscript{2009} and references therein). It induces and influences various types of angular momentum transport and chemical mixing processes inside the star, such as shear mixing (e.g., Heger et al.\textsuperscript{2000}, Mathis et al.\textsuperscript{2004}, Maeder et al.\textsuperscript{2013}), meridional circulation (e.g., Zahn\textsuperscript{1992}, Maeder & Zahn\textsuperscript{1998} (Mathis & Zahn\textsuperscript{2004}) and waves (e.g., Lee & Said\textsuperscript{1993}, Talon & Charbonnel\textsuperscript{1998, 2003}, Mathis\textsuperscript{2009}, Rogers\textsuperscript{2015}). These lead to additional transport of fuel into the nuclear burning regions, influencing the nucleosynthesis and extending the life of the star (e.g., Zahn\textsuperscript{1992}, Pinsonneault\textsuperscript{1997}, Maeder & Meynet\textsuperscript{2000}). The mixing processes also have a potential impact on the element abundances at the stellar surface (e.g., Brott et al.\textsuperscript{2011a,b}).

Furthermore, stellar rotation has a strong influence on stellar magnetism (e.g., Mestel\textsuperscript{1999}, Spruit\textsuperscript{1999} and vice versa (e.g., Mestel et al.\textsuperscript{1988}, Spruit\textsuperscript{1999}, Mathis & Zahn\textsuperscript{2005}). The centrifugal acceleration distorts the shape of the star (e.g., Roxburgh\textsuperscript{2004}, Jackson et al.\textsuperscript{2003}, Roxburgh\textsuperscript{2006}, MacGregor et al.\textsuperscript{2007}, Espinosa Lara & Rieutord\textsuperscript{2013}), and the distribution of angular momentum influences the convective stability inside the star (e.g., Maeder et al.\textsuperscript{2013}).

The full impact of stellar rotation is far from understood (e.g., Aerts et al.\textsuperscript{2014}, Cazola et al.\textsuperscript{2017}). While there have been considerable efforts to do multi-dimensional stellar modelling (e.g., Rieutord et al.\textsuperscript{2016}), these often have a high computational cost. Hence, state-of-the-art stellar evolution codes typically use one-dimensional stellar models in which higher dimensional processes such as stellar rotation are averaged over isobars.
Thanks to recent photometric space missions such as MOST (Walker et al. 2003), CoRoT (Xuvergne et al. 2009), Kepler (Burudici et al. 2010; Koch et al. 2010), K2 (Howard et al. 2014), and BRITE (Weiss et al. 2014; Pablo et al. 2016), there has been significant progress in constraining stellar rotation using observations. These high-quality high-cadence and long time-base data have led to major advances in asteroseismology, i.e., the study of the internal stellar structure, dynamics and evolution by analysing non-radial stellar pulsations. This has been particularly successful for low-mass main-sequence stars with radiative cores and convective envelopes (e.g., Benomar et al. 2015; van Saders et al. 2016), subgiants (e.g., Deheuvels et al. 2014), and red giants (e.g., Beck et al. 2012; Deheuvels et al. 2012; Ceillier et al. 2017). However, asteroseismology is also a valuable tool to study intermediate- to high-mass main sequence stars with convective cores and radiative envelopes.

During their evolution, stars enter different phases in which their rotation dynamics are different. In the first dynamical regime, stars are in their main-sequence phase, with a rotation period in the range of 2 days (Saio et al. 2015). As they evolve, they enter the horizontal branch phase, which is characterized by rotational periods of the order of days (Chaboyer et al. 1995; Heger et al. 2000; Eggenberger et al. 2008; Ekstrom et al. 2012; Chelli & Limongi 2013; Paxton et al. 2013; Marques et al. 2013; Palacios et al. 2003; Charbonnel & Lagarde 2010; Amard et al. 2016). This approach is often incomplete, and potentially numerically unstable (e.g., Lai et al. 2014; Lattanzio et al. 2015; Rieutord et al. 2016; Edelmann et al. 2017).

In this work, we aim to constrain possible radial differential rotation in γ Dor stars. We study the problem using two different approaches. First, we take a closer look at the theoretically expected effects of differential rotation in the near-core regions on the g-mode pulsations (Section 2.1 and Appendix A), and use them to place a constraint on the differential rotation observed by γ Dor stars (Section 2.3). Second, we determine the core-to-surface rotation ratio for stars in the same sample using rotational spot modulation (Section 3) to constrain the stellar surface rotation rate. Finally, we will discuss these results, and draw our conclusions (Section 4).

2. Differential rotation in the near-core regions

2.1. Theoretical description of the g-modes

Computing the complete impact of stellar rotation on pulsations is computationally expensive (Dintrans & Rieutord 2000; Balot et al. 2010). A common method to reduce this computational cost for g-mode pulsations is to use the traditional approximation of rotation (TAR), whereby (i) the horizontal component of the stellar rotation vector in the equation of motion is ignored, and (ii) the studied star is assumed to be spherically symmetric (e.g., Eckart 1960; Friedlander 1987; Lee & Saio 1987; 1997; Townsend 2005; Mathis 2009 and Appendix A). For slow to moderate rotators where the stratification restoring force dominates the Coriolis acceleration along the radial direction, these assumptions are reasonable. The horizontal component of the pulsation displacement vector (and velocity) is dominant for g-modes, which are most sensitive to the near-core regions in the star where the deformation of the stellar structure caused by the centrifugal force is minimal.

When the star is assumed to be rigidly rotating, the g-mode pulsation periods in the corotating reference frame are given by

\[ P_{\text{co}} = \frac{\Omega}{\sqrt{\nu_{\text{lim}}} (n + \alpha_g)} \]

with

\[ \Pi_0 = 2\pi^2 \int_1^r \frac{d r}{r^2} \]

as described by Bouabid et al. (2013). Here, \( N \) is the stable stratification Brunt-Väisälä frequency defined in Appendix A, \( \lambda_{\text{d集中在}}\) is the eigenvalue of the Laplace Tidal Equation, and \( \nu \) the corresponding spin parameter given by \( \nu = 2\Omega f_{\text{rot}} P_{\text{co}} \), with \( f_{\text{rot}} = \frac{\Omega}{\Omega_{\text{rot}}} \) the rotation frequency (\( \Omega \) being the rotation angular velocity). The integers \( k \) and \( m \) provide the pulsation mode identification as defined by Lee & Saio (1997), i.e., \( k = l - |m| \) for g-modes, whereby \( l \) is the spherical degree of the pulsation mode, and \( k < 0 \) for purely inertial modes; \( n \) is the integer corresponding to the quantification along the radial direction. \( \alpha_g \) is a phase term dependent on the stellar structure at the boundaries of the pulsation mode cavity. For stars with a convective core and convective envelope, \( \alpha_g \approx 0.5 \). The turning points of the pulsation mode cavity are indicated by \( r_1 \) and \( r_2 \).

Eq. (1) can be generalised for purely radial differential rotation (the so-called shellular rotation), where the angular velocity...
is a function of \( r \) only. Using the asymptotic theory for the propagation of low-frequency gravito-inertial modes in differentially rotating stars developed by Mathis (2009) (see also Ogilvie \\& Lin 2004) and detailed in Appendix A, one can show that

\[
2\pi^2 \left( n + \alpha_g \right) = \int_{1}^{\infty} \frac{\sqrt{\nu_{\text{km}}(r)}}{f_{\text{in}} - mf_{\text{rot}}(r)} \frac{N(r)}{r} \, dr,
\]  

(3)

where \( f_{\text{in}} \) is the frequency of the pulsation with mode identification \((n,k,m)\) as seen by the observer in the inertial reference frame. Here, both the eigenvalue \( \lambda_{\text{km}} \) and the rotation profile \( f_{\text{rot}}(r) \) vary as a function of the radial coordinate \( r \), and are included within the integral.

We see from Eq. (3) that small variations in the stellar rotation profile or in the Brunt-Väisälä frequency profile have a comparable effect on the pulsation frequencies. This can be illustrated by the case of a weak radial differential rotation defined as in Mathis et al. (2008)

\[
f_{\text{rot}}(r) = f_{\text{ini}} + \delta f(r) = \frac{1}{2\pi} \left( \Omega_{\text{ini}} + \delta \Omega(r) \right) \quad \text{with} \quad \delta \Omega(r) \ll \Omega_{\text{ini}},
\]

(4)

In this case, Eq. (3) becomes

\[
2\pi^2 \left( n + \alpha_g \right) \approx \sqrt{\lambda_{\text{km},s}} \int \frac{N(r)}{r} \left[ 1 + \bar{e}(r) \right] \, dr,
\]

(5)

where \( \nu_{\text{ini}} = 2f_{\text{ini}}/f_{\text{co}}, \quad \bar{e}(r) = m f_{\text{rot}}(r) \) and \( e(r) = m \delta f(r)/f_{\text{co}}-m f_{\text{rot}}(r) \).

In addition, we can further explore the impact of differential rotation, by rewriting Eq. (3) using Taylor expansions for \( \sqrt{\lambda_{\text{km}}(r)} \) and \( (f_{\text{in}} - mf_{\text{rot}}(r))^{-1} \) at a radial coordinate \( r_i \), where the sensitivity of the g-modes to the stellar structure is dominant. This leads to

\[
\Pi_0 \left( n + \alpha_g \right) \approx \frac{\lambda_{\text{km},s}}{f_{\text{co},s}} \left\{ 1 + \left( \frac{\lambda_{\text{km},s}}{2f_{\text{rot},s}} + \frac{mf_{\text{rot},s}}{f_{\text{co},s}} \right)(r - r_i) \right. \\
+ \left. \left( \frac{\lambda_{\text{km},s}}{2f_{\text{rot},s}} - \frac{\lambda_{\text{km},s}}{2f_{\text{rot},s}} \right)^2 + \frac{mf_{\text{rot},s}}{f_{\text{co},s}}(r - r_i) \right\} \times \left( \int r_i dr \right)^{-1}
\]

(6)

Here the quantity \( x \), \( x^\prime = dx/dr \), and

\[
(\bar{x}) = \left( \int_{r_i}^{r_i} \frac{N(r)}{r} \, dr \right) \left( \int_{r_i}^{r_i} \frac{N(r)}{r} \, dr \right)^{-1}.
\]

The pulsation frequency in the local corotating frame is given by

\[
f_{\text{co}}(r) = f_{\text{ini}} - mf_{\text{rot}}(r).
\]

(7)

Because the eigenvalue \( \lambda_{\text{km}} \) varies smoothly as a function of the spin parameter \( \nu \) for a given pulsation mode identification \((k,m)\), the derivatives in the right-hand side of Eq. (6) can be rewritten using the chain rule. Hereby we consider the functions \( \lambda_{\text{km}}(\nu), \nu(f_{\text{rot}}) \) and \( f_{\text{rot}}(r) \) for a given pulsation. Taking into account that the pulsation period in the corotating frame \( P_{\text{co},s} = f_{\text{co},s} \), we find

\[
\Pi_0 \left( n + \alpha_g \right) \approx \sqrt{\lambda_{\text{km},s}} \left( P_{\text{co},s} + \sum_{i=1}^{3} a_i G_i(\nu) P_{\text{co},s}^{\nu+1} \right),
\]

(8)

The coefficients \( a_i \) depend on the rotation profile, and are the same for all pulsations. The functions \( G_i(\nu) \) depend on the pulsation mode identification, and describe how the influence of the differential rotation varies across the period spacing patterns. The full expressions for \( a_i \) and \( G_i(\nu) \) are given in Appendix B.

Because the functions \( G_i(\nu) \) are continuous and smooth, we can conclude that differential rotation in the near-core regions of a g-mode pulsator also introduces an additional continuous change in the slope of the period spacing patterns.

### 2.2. MESA & GYRE models

We illustrate the theoretical results from Section 2.1 by computing pulsation periods for stellar evolution models including a differential rotation profile. The input models are computed with the one-dimensional stellar evolution code MESA v10108 ( Paxton et al. 2011, 2013, 2015, 2018), for a non-rotating 1.7 \( \odot \) star with solar metallicity, assuming the chemical mixture described by Asplund et al. (2009) and using OPAL opacity tables (Rogers & Nayfonov 2002). Convection is treated using the mixing length theory, with an \( \alpha_{\text{MLT}} \) value of 1.8, exponential convective core overshooting of 0.015 \( H_\star \), and extra diffusive mixing in the radiative region of 1 cm\(^2\) s\(^{-1}\). These values were chosen to match the ones used in studies of g-mode pulsators observed with space photometry (e.g., Moravveji et al. 2015, 2016; Schmid & Aerts 2016; Zwintz et al. 2017). The differential rotation profile is added a posteriori to the model. It is defined as

\[
f_{\text{rot}}(r) = f_{\text{rot},s} \left[ 1 + \delta f \left( \int_{r_0}^{\nu(r)} \frac{N(r)}{r} \, dr \right) \left( \int_{0}^{\nu(r)} \frac{N(r)}{r} \, dr \right)^{-1} \right],
\]

(9)

where \( r_s = (r) \), and \( f_{\text{rot},s} \) and \( \delta f \) are free parameters, providing the rotation frequency at radius \( r_s \) and the relative difference in rotation frequency between \( r = 0 \) and \( r = r_s \), respectively. This prescription is based on the differential rotation profile derived by Rieutord (2006) and Hypolite & Rieutord (2014) for the thermal wind balance in rapidly rotating stars, taking into account the effects of rotation and stable stratification in the Boussinesq approximation.

We evaluated the asymptotic relation in Eq. (3) for different theoretical stellar models, and compared our results with full numerical pulsation frequencies computed for the same input models. For the evaluation of Eq. (3), we relied on the numerical Brunt-Väisälä frequency profiles. The pulsations of the stellar models were calculated at multiple points during the main-sequence evolution (with a core mass hydrogen fraction \( X_c \) of 0.7, 0.5, 0.3, and 0.1, respectively), for several rotation rates \( f_{\text{rot},s} = 0.1 \text{d}^{-1}, 1 \text{d}^{-1}, 1.5 \text{d}^{-1}, \) and \( 2 \text{d}^{-1} \) with varying degrees of differential rotation. The numerical pulsation frequencies of the stellar models were computed using the adiabatic version of the stellar pulsation code GYRE v5.1 (Townsend & Teitler 2013, Townsend et al. 2018), since stability or excitation rate computations (see, e.g., Bouabid et al. 2013) are beyond the scope of the present work. This version of the GYRE code adopts the TAR to model gravito-inertial and purely inertial modes. The implementation of the TAR in GYRE, which was undertaken independently of the present work, is similar to the approach described by Townsend (2005), with the allowance for differential rotation as derived by Mathis (2009).

In most cases, our test results were qualitatively similar. A representative case is shown in Fig. 1. While the asymptotic relation in Eq. (3) does not account for mode trapping, it describes
the changes in the mean pulsation period and the slope of the period spacing patterns, caused by differential rotation. The results from Eq. (5) and those obtained numerically with the GYRE code are in agreement.

The impact of the differential rotation on the pulsation modes depends on the pulsation mode identification. For retrograde gravito-inertial modes, such as r-modes with \((k, m) = (-2, -1)\), the local pulsation frequency in the co-rotating frame is lower when the local rotation frequency is lower, and vice versa, as we can see from Eq. (7). For prograde modes, the local pulsation frequency in the co-rotating frame increases when the local rotation frequency increases. The relative contribution of the Coriolis force to the total restoring force increases when the local pulsation frequency in the co-rotating reference frame decreases. Hence, retrograde (prograde) modes become more sensitive to the slower (faster) rotating layers in a differentially rotating star. Thus, if the stellar core rotates sufficiently faster than the outer layers, as illustrated in Fig. [1], the retrograde r-modes are more sensitive to the outer layers of the star, whereas the prograde gravito-inertial modes are more sensitive to the near-core regions, as illustrated in Fig. [2]. Finally, as we can see in Fig. [1], changes in the rotation profile cause the dips in the period spacing patterns to shift in period. This is also indicative of changes in the pulsation mode cavities.

Other illustrative examples of the impact of differential rotation on g-mode period spacing patterns can be found in the Appendix, in Figs. [C.1] and [C.2].

### 2.3. Revisiting the \( \gamma \) Dor sample analysis

We now reanalyse the period spacing patterns of \( \gamma \) Dor stars reported by Van Reeth et al. (2015), and consider the possibility of radial differential rotation. These stars have been studied in an ensemble modelling analysis by Van Reeth et al. (2016), assuming rigid rotation. This was successful for 40 of the 50 stars with observed period spacings, and led to the identification of r-mode pulsations in ten stars in the sample. These results were recently confirmed in further analyses by Saio et al. (2018).

In a first step, we fit the observed period spacing patterns using Eq. (8), whereby we optimise the parameters \( \Pi_0 \), \( f_{\text{rot},0} \), and \( a_i \). From this analysis we find that the observed period spacing patterns often do not allow to detect differential rotation. This is illustrated in Fig. [3] for the \( \gamma \) Dor star KIC 11721304, where we show the observed pattern, the best fitting model assuming rigid rotation, and a model that includes differential rotation. The quality of the fit is similar for both types of rotation profiles, but when differential rotation is included, the uncertainties on the derived near-core rotation rate and the asymptotic spacing become

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**Fig. 1.** The 1.7 \( M_\odot \) stellar model at \( X_e = 0.7 \) with \( f_{\text{rot},0} = 2 \, \text{d}^{-1} \) and \( \delta f = 0.0 \) (light grey), 0.1 (grey), and 0.2 (black). Top left: The considered stellar rotation profiles. Left: The corresponding gravito-inertial mode pulsations with \((k, m) = (+0, +1)\), computed from Eq. (5) (middle) and with GYRE v5.1 (bottom). Right: The corresponding gravito-inertial mode pulsations with \((k, m) = (-2, -1)\), computed from Eq. (5) (middle) and with GYRE v5.1 (bottom).

**Table 1.** The parameter values of the simulations shown for KIC 11721304 and KIC 12066947 in Figs. [A.1] and [A.2] compared with the parameter values of the best model assuming rigid rotation.

<table>
<thead>
<tr>
<th>( \Pi_{0,\text{sim}} ) [s]</th>
<th>( f_{\text{rot},0,\text{sim}} ) [d(^{-1})]</th>
<th>( \delta f_{\text{sim}} )</th>
<th>( \Pi_{0,\text{model}} ) [s]</th>
<th>( f_{\text{rot},0,\text{model}} ) [d(^{-1})]</th>
<th>( \chi^2_{\text{red}} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>KIC 11721304</td>
<td>4328</td>
<td>0.458</td>
<td>0</td>
<td>4350(230)</td>
<td>0.459(13)</td>
</tr>
<tr>
<td></td>
<td>4105</td>
<td>0.339</td>
<td>0.88</td>
<td>4800(330)</td>
<td>0.483(16)</td>
</tr>
<tr>
<td>KIC 12066947</td>
<td>4180</td>
<td>2.16</td>
<td>0.0</td>
<td>4180(60)</td>
<td>2.161(4)</td>
</tr>
<tr>
<td></td>
<td>4152</td>
<td>2.14</td>
<td>0.04</td>
<td>4110(50)</td>
<td>2.153(4)</td>
</tr>
<tr>
<td></td>
<td>3965</td>
<td>0.458</td>
<td>0.0</td>
<td>3950(120)</td>
<td>0.459(13)</td>
</tr>
</tbody>
</table>
Fig. 2. The pulsation mode cavities of the gravito-inertial mode pulsations with \((n, k, m) = (-25, +0, +1)\) (black) and \((n, k, m) = (-25, -2, -1)\) (grey) for the \(1.7 M_\odot\) stellar model at \(X_c = 0.7\) with \(f_{\text{rot}} = 2\,\text{d}^{-1}\), shown in Fig. 1. Both the integrand of Eq. \((3)\) (left) and the rotation kernel \(K_\omega\) (computed following Eq. \((3.356)\) in Aerts et al. \((2010)\); right) are shown for differential rotation rates \(\delta f = 0.0\) (top), 0.1 (middle), and 0.2 (bottom).

Fig. 3. The observed period spacing pattern of KIC 11721304 (grey squares) with the best model assuming rigid rotation (red; \(f_{\text{rot}} = 0.46 \pm 0.02\,\text{d}^{-1}, \Pi_0 = 4320 \pm 230\,\text{s}\), and allowing for differential rotation (blue; \(f_{\text{rot}} = 0.51\,\text{d}^{-1}, \Pi_0 = 4430\,\text{s}, a_1 = -0.04\)).

larger. Hence, the model assuming rigid rotation is statistically favourable, but we cannot disprove differential rotation.

To properly establish the extent of this degeneracy, we simulate period spacing patterns for varying degrees of differential rotation, and analyse them using rigidly rotating models. The simulated period of the pulsation with mode identification \((n, k, m)\) in the inertial reference frame, is given by

\[
P_{nkm} = P_{\text{th,nkm}} + \delta P_{nkm}. \tag{10}
\]

Here, \(P_{\text{th,nkm}}\) is the theoretical pulsation period for the mode \((n, k, m)\) in the asymptotic regime, computed with Eq. \((3)\). We used the \(1.7M_\odot\) MESA model discussed in Section 2.2 at \(X_c = 0.5\) as input, combined with rotation profiles that were constructed following Eq. \((9)\) for increasing differential rotation rates \((0 \leq \delta f \cdot f_{\text{rot,s}} \leq 0.3)\). The offsets \(\delta P_{nkm}\) in Eq. \((10)\) account for the effects of mode trapping and observational errors that were included in our simulated data. The latter were taken to be the residuals after modelling an observed period spacing pattern. These simulated period spacing patterns were subsequently fitted with a rigid rotation model, as described by Eq. \((1)\), and the quality of the fits were evaluated using reduced \(\chi^2\)-values.

The results of two selected simulations, with offsets \(\delta P_{nkm}\), based on the observations of the \(\gamma\) Dor star KIC 11721304, are shown in Fig. 4 and listed in Table 1. As the differential rotation \(\delta f\) in the simulated data increases, the quality of the rigidly

Fig. 4. Simulated period spacing patterns based on the observations for KIC 11721304 (black dots). The input parameters for the simulations (with non-rigid rotation) are shown in black, while the \(\chi^2_{\text{red}}\) of the best model with rigid rotation (full red line) is also given.
rotating model fit decreases. However, this is hard to observe. Indeed, differences in the slope of the simulated pattern caused by the differential rotation are accounted for by slight changes in the near-core rotation rate \( f_{\text{rot1}} \) and asymptotic spacing \( \Pi_0 \) of the rigidly rotating model. The changes in the model value of \( \Pi_0 \) are related to the interaction between the differential rotation profile and the Brunt-Väisälä frequency profile, as we derived from Eq. (2) and illustrated in Fig.2. For all simulated differential rotation profiles, the values for \( f_{\text{rot1}} \) and \( \Pi_0 \) of the best model are as typically detected for a \( \gamma \) Dor star. Any remaining differences between the differentially rotating simulation \( f_{\text{rot2km}} \) and the best fitting model are negligible compared to the offsets \( \Delta P_{\text{rot}} \). As a result, we cannot properly detect the differential rotation in these simulated data, even for \( \delta f \approx 0.9 \).

The degeneracy between rigid and differential rotation is lifted when multiple period spacing patterns are observed for the same star. This is illustrated in Fig.5. Here we have simulations of a prograde dipole mode series and a retrograde \( r \)-mode series, with offsets \( \Delta P_{\text{rot}} \) based on the observations of the \( \gamma \) Dor star KIC 12066947. The parameter values of the simulated patterns and the best (rigidly rotating) models are again listed in Table[1]. Because a differential rotation profile has a different effect on both patterns (as discussed in Section 2.2), its presence is revealed when models assuming uniform rotation are fitted simultaneously to the data. We can see that for the simulations in the bottom panels of Fig.5 with \( \delta f = 0.15 \), the rigidly rotating model fails to match the slope of the patterns. Since we did not observe such significant shortcomings when modelling the real observed period spacing patterns for this star, we estimate that its differential rotation rate is \( \delta f \leq 0.15 \). Similar model-dependent upper limits for \( \delta f \) have been estimated for the other stars with detected \( r \)-mode patterns, and are listed in Table3.

In addition, the simulations illustrate another property when dealing with non-rigid rotation. The uniformly rotating model provides a better fit to the simulated data with a differential rotation rate \( \delta f = 0.04 \), than to the simulated data for a rigid rotor \( \delta f = 0.0 \), as evidenced by their respective \( \chi^2_{\text{red}} \) values. For \( \delta f = 0.04 \), the observational signatures of pulsation mode trapping by a chemical gradient and the differential rotation partially cancel each other. Modelling of the patterns in Fig.5 individually confirms these results and is in line with the discussion in Section 2.2. As the differential rotation increases, the prograde gravito-inertial modes become more sensitive to the faster rotating near-core regions, and the \( r \)-modes become more sensitive to the slower rotating outer layers of the star. At the differential rotation rate \( \delta f = 0.15 \), the results from modelling both patterns individually no longer agree within their respective errors. In addition, the \( r \)-modes have become sufficiently sensitive to the outer layers of the star that the derived asymptotic spacing \( \Pi_0 \) from the modelling, as computed in Eq. (2), is no longer reliable.

2.4. Discovery of Yanai modes

For ten stars in the sample, Van Reeth et al. (2016) could not find a unique pulsation mode identification for the detected period spacing patterns. For some, there were multiple mode identifications that yielded equally good results. However, for six of them, no suitable interpretation could be found at all. Interestingly, all of these stars have a few characteristics in common. They have low to moderate values for the spectroscopic rotation velocity \( v \sin i \) (see Table2). For each of them, Van Reeth et al. (2015) detected a single period spacing pattern with an upward slope, i.e. of retrograde pulsation modes, with period spacing values typically ranging from a few hundred to a few thousand seconds. Qualitatively, these characteristics agree with what is expected for Yanai modes, a type of purely inertial pulsation modes with \( k = -1 \), otherwise known as odd \( r \)-modes (Townsend 2003b; Saio et al. 2018). The observed period spacing values are far larger than the spacings of \( r \)-modes with \( k = -2 \), while the spacings of normal retrograde \( g \)-modes with \( k \geq 0 \) are not expected to be much smaller than the asymptotic spacing \( \Pi_0 / \sqrt{l(l+1)} \). However, Van Reeth et al. (2016) could not compute a satisfactory theoretical model for Yanai modes, and were limited to the asymptotic expressions given by Townsend (2003b).

In this work, we are able to compute adequate theoretical models for Yanai modes, using GYRE v5.1. The period spacing pattern of the \( \gamma \) Dor star KIC 11668783 is shown in Fig.6 as an example. The best fitting model, included in the figure, corresponds to Yanai modes with \( (k,m) = (-1,-1) \) in a rigidly rotat-
ing star. While we can obtain pulsation periods in the observed range, the slope of the model pattern differs from the slope of the observations, and the asymptotic spacing $\Pi_0$ and near-core rotation frequency $f_{\text{rot}}$ of our best model have unrealistic values, i.e., $2300^{+790}_{-300}$ s and $1.99^{+0.05}_{-0.15}$ d$^{-1}$ respectively. The inclusion of radial differential rotation in the models was insufficient to resolve this issue.

However, the observations are qualitatively consistent with Yanai modes with $(k, m) = (-1, -1)$. If we assume that the star is a solid body rotator, we can use the mode identification to derive a lower limit for the stellar rotation frequency $f_{\text{rot}}$. As explained in detail by Saio et al. (2018), an $r$-mode pulsation frequency in the inertial reference frame $f_{\text{in}} < |m|f_{\text{rot}}$, so that for $m = -1$, we have $\langle |m|f_{\text{min}} \rangle = f_{\text{rot}}$, where $P_{\text{min}}$ is the shortest pulsation period of the detected period spacing pattern. Combined with the spectroscopic values for the projected surface rotation velocity $v \sin i$, we find that these are moderate to fast rotators seen close to pole-on. These results, shown in Figs. 7 and 8, are generally consistent with the theoretical expectations for Yanai modes (Saio et al. 2018).

Table 2. The six stars with single retrograde period spacing patterns, that we suspect correspond to Yanai modes. The listed parameters include the spectroscopic rotation velocity, the dominant pulsation frequency, and the minimum and maximum pulsation periods for the pulsations in the detected period spacing patterns.

<table>
<thead>
<tr>
<th>KIC</th>
<th>$v \sin i$ [km s$^{-1}$]</th>
<th>$f_{\text{dmo}}$ [d$^{-1}$]</th>
<th>$P_{\text{min}}$ [days]</th>
<th>$P_{\text{max}}$ [days]</th>
</tr>
</thead>
<tbody>
<tr>
<td>4757184</td>
<td>36(3)</td>
<td>1.26725(2)</td>
<td>0.69939(4)</td>
<td>1.00612(7)</td>
</tr>
<tr>
<td>5350958</td>
<td>28(2)</td>
<td>2.158409(4)</td>
<td>0.58249(2)</td>
<td>1.36381(8)</td>
</tr>
<tr>
<td>6185513</td>
<td>83(6)</td>
<td>2.245965(7)</td>
<td>0.50812(2)</td>
<td>1.3940(1)</td>
</tr>
<tr>
<td>6425437</td>
<td>50(3)</td>
<td>0.896811(1)</td>
<td>0.69305(6)</td>
<td>1.2640(2)</td>
</tr>
<tr>
<td>7867348</td>
<td>17(1)</td>
<td>1.16998(1)</td>
<td>1.14962(2)</td>
<td>1.8273(2)</td>
</tr>
<tr>
<td>11668783</td>
<td>34(3)</td>
<td>0.627995(7)</td>
<td>1.12644(4)</td>
<td>1.65470(8)</td>
</tr>
</tbody>
</table>

There are differences between the models and the observations for these six stars. These stars are fast rotators, seen close to pole-on as indicated by the low $v \sin i$ values. Hence, the traditional approximation may not be applicable to Yanai modes in these stars. The behaviour of Yanai modes becomes similar to that of retrograde gravity-modes at high spin parameter values (Townsend 2003b; Saio et al. 2018). Recently, Ouazzani et al. (2017) compared the traditional approximation with a general two-dimensional treatment of stellar pulsations and found that it is reasonably appropriate for g-mode period spacing patterns with various mode identifications, except for retrograde g-modes in moderate to fast rotating stars. In this case, general two-dimensional models are needed.
3. Rotational modulation 

A common approach to observationally detect or disprove differential rotation is to determine the ratio between the rotation frequency in the near-core regions and close to or at the stellar surface. While g-mode pulsations are the only reliable way to probe the stellar properties near the convective core, the rotation rate in the outer stellar envelope can be determined by analysing p-mode pulsations (e.g., Kurtz et al. 2014; Sato et al. 2015; Schmid & Aerts 2016) and/or rotational spot modulation (e.g., Degroote et al. 2011; Escorza et al. 2016; Sato et al. 2018) in the light curve, if either are present. In this section, we focus on detecting rotational modulation and distinguishing it from g-mode pulsations. To avoid confusion, the rotation frequency in the deep stellar interior and in the outer layers are denoted by \( f_{\text{rot},i} \) and \( f_{\text{rot},o} \), respectively.

When we look for observational signatures of rotational spot modulation in the Fourier spectrum of space-based photometry of a star, we expect to find low-frequency peaks for which the 1st harmonic frequency is present as well. These frequencies are often part of a group of two or more closely spaced frequencies which are not always resolved. Such signal is common for low-mass stars with convective envelopes, but has been observed for A- and B-type stars as well (e.g., Degroote et al. 2011; Escorza et al. 2016; Bowman 2017; Sato et al. 2018).

For non-radial g-mode pulsators, the detection of rotational modulation signal is not straightforward. These pulsation modes are known to have combination frequencies in the observations, and, for main-sequence stars, they occur in the same frequency range as the stellar rotation frequency. Furthermore, we may expect similar amplitudes for rotational modulation and g-mode pulsations in photometric data, and both types of signal are frequently non-sinusoidal. However, contrary to g-mode pulsations, which have lifetimes longer than the total observation time of the *Kepler* space mission, rotational spot modulation can vary in amplitude on much shorter timescales. In addition, whereas g-mode pulsations have very stable frequencies on long timescales, rotational spot modulation frequencies often exhibit small variations dependent on the latitude of the stellar spots. Consequently, rotational modulation signal oftentimes consists of isolated closely spaced frequency groups, clustered around harmonic frequencies.

Hence, we evaluate the frequencies extracted from the *Kepler* photometry by Van Reeth et al. (2015) to look for rotational modulation signal. To properly distinguish g-mode pulsations from rotational modulation, we require that

- the signal-to-noise ratio \( S/N \geq 4 \), and the value of the amplitude is at least five times as large as its error, to ensure that the detected signal is significant,
- the first harmonic of the selected frequencies is detectable in the data, whereby we use the Rayleigh frequency resolution \( f_{\text{res}} \) as a limit to find harmonics,
- the selected frequency is part of a closely spaced group of frequencies, whereby \(|f_i - f_j| < 1.5f_{\text{res}}\),
- both the selected frequencies and their first harmonics are located outside of the frequency ranges of the g-mode pulsation frequencies and their combinations,
- the selected frequencies are larger than half the derived near-core rotation frequency \( f_{\text{rot},i} \) and any detected r-mode frequencies,
- the selected frequencies are smaller than one-and-a-half times the derived near-core rotation frequency \( f_{\text{rot},i} \) and any detected prograde pulsation mode frequencies.

With these criteria, the main limitation is that stellar spots must have a shorter lifetime than the total observation time of the original *Kepler* space mission. This implies that we cannot detect rotational modulation in g-mode pulsators with long-lived stellar spots. A second limitation of our approach is that we require the surface rotation rate and the near-core rotation rate to agree within 50%. This assumption would be unjustified in (very) slowly rotating stars, such as KIC 8197761 (Sowicka et al. 2017). However, the stars in our sample rotate significantly faster (Van Reeth et al. 2016).

Our analysis is illustrated in Fig. 9 for the γ Dor star KIC 11294808. The frequencies marked in red are the only peaks that fulfill the three criteria, and any frequencies within the grey area fulfill the last two criteria. There is only one peak, at 0.788 ± 0.001 d\(^{-1}\), that satisfies all of our criteria, and is reasonably isolated within the frequency spectrum. Thus, this signal is caused by rotational modulation, and its frequency is the surface rotation rate \( f_{\text{rot},o} \). Consequently, \( f_{\text{rot},o} \) and \( f_{\text{rot},i} \) are equal within 1\(\sigma\), indicating that KIC 11294808 is a rigid rotator.

To avoid false detections, our employed criteria for the detection of rotational modulation are rather strict. However, when one of the criteria is not met for a star, it can still exhibit rotational modulation. As an example, we show the Fourier spectrum of the γ Dor star KIC 8375138 in Fig. 10. There is a small-amplitude peak in the spectrum at a frequency of 1.641 ± 0.001 d\(^{-1}\) that complies with all but one of our criteria, i.e., it is not part of a closely spaced group of frequencies, but an isolated frequency. Nevertheless, this is very likely also rotational modulation signal. Thanks to the detection of both prograde dipole modes and r-modes in this star, the near-core rotation rate \( f_{\text{rot},i} \) is exceptionally well-constrained, and the detected frequency agrees with \( f_{\text{rot},i} \) within a fraction of 1\(\sigma\). The probability that this is a pulsation frequency, is very small. As shown in Fig. 10 we numerically calculated the cumulative distribution function of the detected significant frequencies of this star, that have a first-order harmonic. By drawing random frequency values from the computed distribution function, taking into account the total number of such detected frequencies, we find that there is a 2.1% chance that a significant pulsation frequency with a first-order harmonic in the data, is located within 1\(\sigma\) of \( f_{\text{rot},i} \). The probability of detecting a random significant pulsation frequency with a first-order harmonic within 3\(\sigma\) of \( f_{\text{rot},i} \) is 7.1%.

All stars with derived values for the surface rotation rate \( f_{\text{rot},o} \) are listed in Table 3.

4. Discussion and Conclusions 

The aim of this work was to provide observational constraints of differential rotation in a sample of γ Dor stars. We approached this issue using two separate methodologies.

First, we considered the impact of differential rotation on the observational properties of g-mode period spacing patterns. We use a theoretical formalism that allows us to study the properties of low-frequency gravito-inertial modes propagating in differentially rotating stars developed in Mathis (2009) and an extended observation sample of γ Dor stars. In a uniformly rotating star, the slope of an observed period spacing pattern provides information on the stellar rotation rate, while the non-uniform structure of the pattern is a signature of the pulsation mode trapping caused by chemical gradients and discontinuities in the near-core regions. Differential rotation modifies these diagnostics. It changes the sensitivity of pulsation modes to different depths within the interior structure, which in turn leads to changes in the pulsation mode trapping. This translates into changes of the
morphology of the period spacing patterns. A high differential rotation rate will also change the slope of the observed period spacing pattern. Here, we developed a new theoretical seismic diagnostic for the case of radial differential rotation.

In the case where only one period spacing pattern is detected for a star, it is difficult to detect the signature of differential rotation in the pattern. Indeed, other physical processes, such as the mode trapping by chemical gradients, can have similar observational characteristics in the pulsation period spectrum. On the other hand, a period spacing pattern of a differentially rotating star can often be fitted by a rigidly rotating model, where the uniform rotation rate and asymptotic period spacing parameters of the model are tweaked to compensate for the offset. In many cases the rigidly rotating model is statistically favourable over a model with differential rotation. We demonstrated this for the γ Dor star KIC 11721304, and were unable to detect differential rotation rates below $\delta f < 0.9$.

When multiple period spacing patterns have been detected, the period spacing patterns can be compared to infer the presence of, or an upper limit for, differential rotation. We have demonstrated this for the γ Dor star KIC 12066947, and found $\delta f \lesssim 0.15$. Similar model-dependent upper limits for $\delta f$ have been estimated for our other stars with detected r-mode patterns, and are listed in Table 3.

Second, we have determined surface rotation rates for eight stars in our sample, using detected signal of rotational modulation. From these, we then derived the surface-to-core rotation ratio. Such values have already been computed for other stars in
Table 3. An overview of the stars with derived constraints on differential rotation. The listed values are the near-core rotation rate \( f_{\text{rot,i}} \), estimated model-dependent upper limits on the near-core differential rotation \( \delta f \), the surface rotation rate \( f_{\text{rot,o}} \), and the ratio \( f_{\text{rot,o}} / f_{\text{rot,i}} \).

<table>
<thead>
<tr>
<th>KIC</th>
<th>( f_{\text{rot,i}} ) [d^{-1}]</th>
<th>( \delta f )</th>
<th>( f_{\text{rot,o}} ) [d^{-1}]</th>
<th>( f_{\text{rot,o}} / f_{\text{rot,i}} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>2710594</td>
<td>0.395(8)</td>
<td>0.13</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>3448365</td>
<td>1.079(3)</td>
<td>0.11</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>5114382</td>
<td>1.140(6)</td>
<td>0.15</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>5708550</td>
<td>0.82(2)</td>
<td>-</td>
<td>0.7955(10)</td>
<td>0.97(2)</td>
</tr>
<tr>
<td>6468987</td>
<td>1.546(6)</td>
<td>0.13</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>7365537</td>
<td>2.253(3)</td>
<td>-</td>
<td>2.242(5)</td>
<td>0.995(3)</td>
</tr>
<tr>
<td>7380501</td>
<td>0.64(1)</td>
<td>-</td>
<td>0.6394(10)</td>
<td>1.00(2)</td>
</tr>
<tr>
<td>7583663</td>
<td>1.162(5)</td>
<td>0.16</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>8364249</td>
<td>1.519(8)</td>
<td>-</td>
<td>1.517(5)</td>
<td>0.999(6)</td>
</tr>
<tr>
<td>8375138</td>
<td>1.640(5)</td>
<td>0.12</td>
<td>1.641(1)</td>
<td>1.001(3)</td>
</tr>
<tr>
<td>9210943</td>
<td>1.705(11)</td>
<td>0.07</td>
<td>1.702(15)</td>
<td>0.998(7)</td>
</tr>
<tr>
<td>9480469</td>
<td>1.541(9)</td>
<td>0.04</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>11294808</td>
<td>0.77(2)</td>
<td>-</td>
<td>0.788(1)</td>
<td>1.02(3)</td>
</tr>
<tr>
<td>11456474</td>
<td>1.05(2)</td>
<td>-</td>
<td>1.0495(10)</td>
<td>1.00(2)</td>
</tr>
<tr>
<td>11907454</td>
<td>1.341(3)</td>
<td>0.12</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>12066947</td>
<td>2.159(4)</td>
<td>0.15</td>
<td>-</td>
<td>-</td>
</tr>
</tbody>
</table>

Fig. 11. An overview of BAF-type main sequence stars with derived values for the near-core rotation rate \( f_{\text{rot,i}} \) and the surface rotation rate \( f_{\text{rot,o}} \). The bottom figure is a zoom-in of the top figure. For most stars, the values are consistent with rigid rotation within 1\( \sigma \). The observational signature of differential surface-to-core rotation becomes stronger when the star is slowly rotating, and/or in a binary system. The stars with values from the literature were taken from [Kurtz et al. (2014)], [Sao et al. (2015)], [Suliana et al. (2015)], [Moravjev et al. (2016)], [Murphy et al. (2016)], [Schmid & Aerts (2016)], [Guo et al. (2017)], [Kallinger et al. (2017)], [Sowicka et al. (2017)].

The literature, albeit for more slowly rotating stars. An overview of these stars is shown in Fig. [11]. As we can see, most stars are seemingly uniformly rotating within 1\( \sigma \) or 2\( \sigma \) error margins, and the differential rotation grows larger when (i) the near-core rotation rate is low, or (ii) the star is in a binary system, and sensitive to tidal effects.

When both methods for the detection and constraining of differential rotation in \( \gamma \) Dor stars are combined, we find that the observations are in agreement with (quasi-)rigid rotation throughout most of the radiative region, but that we cannot exclude differential rotation in the near-core regions. The precise location where such differential rotation may be present and the steepness of the gradient can strongly vary, and has to be considered for each studied star individually. When the stellar surface rotation rate is known as well, this can be included as a strong constraint in seismic modelling.

Finally, six stars in the sample exhibit a single retrograde period spacing pattern in qualitative agreement with Yanai modes, for \((k, m) = (−1, −1)\) (Sao et al. 2018). Considering the high rotation frequencies and the associated low inclination angles that this mode identification implies, two-dimensional models that do not assume the traditional approximation, are required to treat these pulsations properly.

This work provides us with a new observational window into the angular momentum transport that takes place in the interiors of intermediate- and high-mass stars with convective cores and radiative envelopes. We derived observational constraints for the rotation profiles in moderate to fast rotating stars, whereas available studies in the literature were mostly limited to slowly rotating stars. Consequently, the results of this work allow us to build a more complete picture of the stellar rotation. This is required to understand which angular momentum transport processes take place inside a star, resulting in the observed dramatic changes in stellar rotation rate during stellar evolution (Aerts et al. 2017; Ouazzani et al. 2018 submitted).

References

Appendix A: Gravito-inertial modes and seismic diagnosis in differentially rotating stars

Appendix A.1: The dynamics of low-frequency gravito-inertial modes within TAR

To treat the dynamics of gravito-inertial modes in a differentially rotating star, we solve the inviscid system formed by the momentum equation

\[ (\partial_t + \Omega \hat{\mathbf{e}}_z) \mathbf{u} + 2 \Omega \hat{\mathbf{e}}_x \times \mathbf{u} + \mathbf{r} \left( \mathbf{u} \cdot \nabla \Omega \right) \mathbf{e}_z = -\frac{1}{\rho} \nabla P - \nabla \Phi + \frac{\rho}{\rho_0} \nabla s, \]

(A.1)

the continuity equation \( \partial_t (\rho \mathbf{u}) + \nabla \cdot (\rho \mathbf{u} \mathbf{u}) = 0 \), the energy transport equation in the adiabatic limit

\[ (\partial_t + \Omega \hat{\mathbf{e}}_z) \left( \frac{P}{\Gamma_1} - \frac{\rho}{\rho_0} \right) + \frac{N^2}{\Gamma_1} (\mathbf{u}), \]

(A.2)

and the Poisson’s equation \( \nabla^2 \Phi = 4\pi G \rho \) (Unno et al. 1989).

\[ \mathbf{u} = (x, \rho, \Phi) \]

are respectively the fluid density, gravitational potential and pressure. Each of them has been expanded as \( X \) (\( \mathbf{r} \), \( \theta \), \( \varphi \), \( t \)) = \( \overline{X} \) (\( \mathbf{r} \)) + \( \tilde{X} \) (\( \mathbf{r} \), \( \theta \), \( \varphi \), \( t \)), \( \overline{X} \) is the mean hydrostatic value of \( X \) on the isobar and \( \tilde{X} \) the wave’s associated linear fluctuation. We introduce the angular velocity \( \Omega (r, \theta) = 2 \pi \Gamma_{\text{fluid}} (r, \theta) \) and the Brunt-Väisälä frequency

\[ N^2 = \lim \left( \frac{\partial \ln T}{\partial \ln P} - \frac{\partial \ln \rho}{\partial \ln P} \right), \]

where \( \Gamma_1 = (\partial \ln P / \partial \ln \rho)_S (S \text{ being the macroscopic entropy}) \) is the adiabatic exponent. \( \mathbf{u} \) is the wave velocity field. Finally, \( (\rho, \theta, \varphi) \) are the usual spherical coordinates with their unit vector basis \( \mathbf{e}_r \) while \( \hat{\mathbf{e}}_z = \cos \theta \mathbf{e}_r - \sin \theta \mathbf{e}_\theta \) is the one along the rotation axis, \( t \) is the time and \( G \) the universal gravity constant.

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To solve this system for low-frequency gravito-inertial modes, four main approximations can be assumed:

- the Cowling approximation: following Cowling (1931), the fluctuation of the gravitational potential (Φ) can be neglected.
- the anelastic approximation: we filter out the high-frequency acoustic modes by simplifying the continuity equation that becomes \( \nabla \cdot (\rho u) \approx 0 \).
- the JWKB approximation: low-frequency modes are such that \( \sigma \ll N (\sigma = 2\pi f_{\text{rot}} \text{ is the wave frequency in an inertial reference frame}) \). Therefore, we are studying modes which are rapidly oscillating along the radial direction and the JWKB approximation can be adopted. Each oscillating quantity is expanded oscillating along the radial direction and the JWKB approximation is given by

\[
\tilde{\Phi}(r, \theta, \phi, t) \approx \tilde{\Phi}(r, \theta) \exp \left[i \int k_y(r') \, dr' \right] \exp \left[i (\sigma t - m \phi) \right] \quad \text{[Ogilvie \\& Lin 2004; Mathis 2009].}
\]

- the Traditional Approximation for Rotation (TAR): stellar radiative zones are strongly stably stratified regions. In the case where the angular velocity (Ω) is reasonably weak compared to the break-up angular velocity, \( \Omega_k = \sqrt{GM/R^3} \), where \( M \) and \( R \) are the stellar mass and radius respectively, we can neglect the centrifugal acceleration at the first order. Moreover, if the stratification restoring force dominates the Coriolis acceleration along the radial direction (i.e. \( 2 \Omega \ll N \)), this allows us to adopt the TAR where the latitudinal component (along \( \theta \)) of the rotation vector \( \vec{\Omega} = \Omega \hat{e}_\theta = \Omega \cos \theta \hat{e}_r - \Omega \sin \theta \hat{e}_\theta \) can be neglected for all latitudes while \( u_r, u_\theta \ll u_{\text{rot}} \). We refer the reader to Friedlander (1987), Ogilvie \\& Lin (2004) and Mathis (2009) for detailed demonstrations.

Under those approximations, Mathis (2009) derived the wave’s velocity field:

\[
u(r, t) = \sum_{j=1,2} \left[ \sum_{k=r,m} u_{j,rkm}(r, t) \right] \hat{e}_j, \quad \text{(A.3)}
\]

where

\[
u_{j,rkm}(r, t) = \frac{\hat{e}_j}{N} \left( \frac{\sigma}{r} A_{rkm}^j(r) \right) \sin \left[ \Psi_{rkm}(r, \varphi, t) \right], \quad \text{(A.4)}
\]

\[
u_{0,rkm}(r, t) = -\frac{\hat{e}_r}{r} G^0_{rkm}(r, \varphi) \cos \left[ \Psi_{rkm}(r, \varphi, t) \right], \quad \text{(A.5)}
\]

\[
u_{1,rkm}(r, t) = -\frac{\hat{e}_\theta}{r} G^1_{rkm}(r, \varphi) \sin \left[ \Psi_{rkm}(r, \varphi, t) \right], \quad \text{(A.6)}
\]

with the Doppler-shifted local frequency (\( \tilde{\sigma} \)) and the spin parameter (see Lee \\& Saio 1997):

\[
\tilde{\sigma}(r, \theta) = \sigma - m \Omega(r, \theta) \quad \text{and} \quad \tilde{\nu}(r, \theta) = \frac{2 \Omega(r, \theta)}{\tilde{\sigma}(r, \theta)}, \quad \text{(A.7)}
\]

Unlike the case of uniform rotation, variables do not separate neatly anymore within TAR in the case of general differential rotations \( \Omega(r, \theta) \), even for shellular rotation laws \( \Omega(r) \) (Mathis 2009). The velocity components are thus expressed in terms of the 2D dynamical pressure \( P/\rho \) eigenfunctions \( w_{rkm} \) which are solutions of the following eigenvalue equation:

\[
O_{\text{lm}} w_{rkm} (r, x) = -\lambda_{rkm} w_{rkm} (r, x), \quad \text{(A.8)}
\]

where we have introduced the General Laplace Operator (GLO)

\[
O_{\text{lm}} = -\frac{1}{\tilde{\sigma}} \frac{d}{dx} \left[ \frac{1}{\tilde{\sigma}^2 \tilde{D}_r(r, x)} \frac{d}{dx} \right] \frac{m^2}{\tilde{\sigma}^2 \tilde{D}_r(r, x)} \left( 1 - x^2 \right) \frac{\partial \Omega}{\partial \tilde{\sigma}} \frac{d}{dx} + \frac{m}{\tilde{\sigma}^2 \tilde{D}_r(r, x)} \frac{\tilde{\nu}_x}{\tilde{\sigma}^2 \tilde{D}_r(r, x)} \left( 1 - x^2 \right) \frac{d}{dx} + m \frac{\tilde{\nu}_x}{\tilde{\sigma}^2 \tilde{D}_r(r, x)} \left( 1 - x^2 \right) \frac{d}{dx}, \quad \text{(A.9)}
\]

We finally solve this system for low-frequency gravito-inertial modes by simplifying the continuity equation that becomes \( \nabla \cdot (\rho u) \approx 0 \), and \( \sigma = \cos \theta \). The GLO is a differential operator in \( x \) only with a parametric dependence on \( r \) and the \( w_{rkm} \) form a complete orthogonal basis

\[
\int_{x} w_{rkm}^* (r, x) w_{rkm} (r, x) \, dx = \delta_{km}, \quad \text{(A.11)}
\]

where \( \delta_{km} \) is the normalization factor and \( \delta_{ikj} \) is the usual Kronecker symbol. The use of the JWKB approximation allows us to reduce the problem of solving a 2D Partial Differential Equation to a Sturm-Liouville problem on co-latitude (\( x \)) for each radius \( r \). The GLO is the generalization of the classical Laplace tidal operator (Laplace 1799), its eigenfunctions \( w_{rkm} \) being thus a generalization of the Hough functions (Hough 1898, Ogilvie \\& Lin 2004). The \( \lambda_{rkm} \) are the eigenvalues. The positive ones correspond to propagative modes for which the dispersion relation is given by

\[
\lambda_{rkm}(r) = \frac{\lambda_{rkm} N^2}{r^2}, \quad \text{(A.12)}
\]

Finally, the latitudinal and azimuthal eigenfunctions are defined by

\[
G_{rkm}^0(r, x) = -\frac{1}{\tilde{\sigma}^2} \frac{d}{d \tilde{\sigma}} \left[ \frac{1}{\tilde{\sigma}^2 \tilde{D}_r(r, x)} \frac{d}{dx} \right] \left[ \frac{1}{\tilde{\sigma}^2 \tilde{D}_r(r, x)} \frac{d}{dx} + m \tilde{\nu}_x \right], \quad \text{(A.14)}
\]

\[
G_{rkm}^1(r, x) = \frac{1}{\tilde{\sigma}^2} \frac{d}{d \tilde{\sigma}} \left[ \frac{1}{\tilde{\sigma}^2 \tilde{D}_r(r, x)} \frac{d}{dx} \right] \left[ \frac{1}{\tilde{\sigma}^2 \tilde{D}_r(r, x)} \frac{d}{dx} + m \tilde{\nu}_x \right] \left[ \frac{1}{\tilde{\sigma}^2 \tilde{D}_r(r, x)} \frac{d}{dx} + m \tilde{\nu}_x \right], \quad \text{(A.15)}
\]

\textbf{Appendix A.2: The case of a radial differential rotation: main properties and period spacing}

We now examine the case of a purely radial differential rotation \( \Omega(r) = 2\pi f_{\text{rot}}(r) \).

In this case, the local frequency and the local spin parameter become:

\[
\tilde{\sigma}(r, \theta) = \sigma - m \Omega(r, \theta) \quad \text{and} \quad \tilde{\nu}(r, \theta) = \frac{2 \Omega(r)}{\tilde{\sigma}(r)}, \quad \text{(A.17)}
\]

where we recall that \( \sigma = 2\pi f_{\text{rot}} \).

\textsuperscript{1} In the case of differential rotation, the possible latitudinal trapping of waves obtained for sub-inertial gravito-inertial waves in uniformly rotating stars will become more complex. We refer the reader to Mathis (2009), Mirouh et al. (2016) and Prat et al. (2018) for a detailed discussion.
The GLO, $O_{\text{lin}}$, then simplifies to the classical Laplace’s tidal operator $L_{\text{lin}}$:

$$O_{\text{lin}} = \frac{1}{\tilde{\sigma}^2(r)} L_{\text{lin}} = \frac{1}{\tilde{\sigma}^2(r)} \frac{d}{dx} \left( \frac{1}{1 - \tilde{\nu}^2(r) x^2} \frac{d}{dx} \right) - \frac{1}{1 - \tilde{\nu}^2(r) x^2} \left( \frac{m^2}{1 - x^2} + m\tilde{\nu}^2(r) \frac{1 + \tilde{\nu}^2(r) x^2}{1 - \tilde{\nu}^2(r) x^2} \right).$$

(A.18)

Its eigenfunctions are the usual Hough’s functions $\Theta_{\tilde{\nu}km}(r, x)$ (Hough 1898) that depend both on $x$ and $r$ in the case of a radial differential rotation through the spin parameter ($\tilde{\nu}$) because it varies along the radius. In other words, we solve the classical Laplace tidal equation for each radius and corresponding values of the rotation angular velocity and spin parameter. In the particular case of a uniform rotation, $\tilde{\nu}$ is independent of $r$ and $x$. The Laplace’s tidal operator thus becomes a linear differential operator in $x$ only with the corresponding purely latitudinal eigenfunctions (e.g. Lee & Sano 1997; Townsend 2003a).

The asymptotic expression of the radial component of the velocity field of low-frequency gravito-inertial modes becomes following Eq. (A.4):

$$u_{r,km}(r,t) = \mathcal{A} \frac{1}{\tilde{\nu}^{1/2}} \frac{\Lambda_{\tilde{\nu}km}(r)}{r} \frac{1}{k_{\nu,\tilde{\nu}km}^{1/2}(r)} \sin[\Psi_{\tilde{\nu}km}(r, \varphi, t)] \times \Theta_{\tilde{\nu}km}(r, x)$$

(A.19)

with

$$k_{\nu,\tilde{\nu}km}^2(r) = \frac{N^2 \Lambda_{\tilde{\nu}km}(r)}{\tilde{\sigma}^2} = \frac{N^2 \Lambda_{\tilde{\nu}km}(r)}{r^2} \quad \text{where} \quad \Lambda_{\tilde{\nu}km}(r) = \tilde{\sigma} \Lambda_{\til\nu km}(r).$$

(A.20)

The eigenvalues for the Laplace’s tidal operator ($\Lambda_{\til\nu km}$) have been related to those of the GLO ($\Lambda_{\til\nu km}$). From now on, $\tilde{\nu}$ becomes $\nu$ in the equations to lighten the notations. We refer the reader to Mathis (2009) for the details of the properties of the latitudinal and longitudinal components of the velocity field. The last step is to write the radial quantification

$$2\pi^2 \left(n + \alpha_e\right) \equiv \int_{r_1}^{r_2} \sqrt[4]{\Lambda_{\til\nu km}(r)} N(r) \frac{r}{f_{\text{lin}} - mf_{\text{rot}}(r)} \, dr,$$

(A.21)

where $n$ is the radial quantum number, that provides the asymptotic frequencies and the period spacing.

**Appendix B: Gravito-inertial modes in the asymptotic regime: Taylor expansion**

As discussed in Section 2.1, we can describe the pulsation periods of the gravito-inertial modes in a differentially rotating star as

$$\Pi_0 \left(n + \alpha_e\right) \approx \sqrt{\Lambda} \left( P_{\text{cos},s} + \sum_{n=1}^{3} a_n G_i(\nu) P_{\text{cos},s}^{n+1} \right).$$

The coefficients $a_n$ in this expression are given by

$$a_1 = f_{\text{rot},s}^{-1} (r - r_s),$$

$$a_2 = f_{\text{rot},s}^{-1} ((r - r_s)^2),$$

$$a_3 = \left(f_{\text{rot},s}^{-1}\right)^2 ((r - r_s)^3).$$

The functions $G_i$ are given by

$$G_1 = \frac{1}{\lambda_s} \left( \frac{d}{d\nu} \right)_s \left( 1 + \frac{m\nu_s}{2} \right) + m,$$

$$G_2 = \frac{1}{\lambda_s} \left( \frac{d}{d\nu} \right)_s \left( 1 + \frac{m\nu_s}{2} \right) + 4m,$$

$$G_3 = \left( \frac{\nu_s}{\lambda_s} \right)^2 \left( \frac{d^2}{d\nu^2} \right)_s \left( 1 + \frac{m\nu_s}{2} \right)^2 + 2m \left( \frac{d}{d\nu} \right)_s \left( 1 + \frac{m\nu_s}{2} \right) + 2m^2.$$
Appendix C: Simulated period spacing patterns

Here, we provide few additional stellar models for which we evaluate the impact of differential rotation on period spacing pattern to complete those already discussed in Sec. 2.2.
Fig. C.1. The 1.7 $M_\odot$ stellar model at $X_c = 0.5$ with $f_{\text{rot}, s} = 1 \, \text{d}^{-1}$ and $\delta f = 0.0$ (light grey), 0.4 (grey), and 0.8 (black), and the corresponding pulsations with $(k, m) = (-1, -1)$. Top left: the Brunt-Väisälä frequency profile. Middle left: The considered stellar rotation profiles. Bottom left: The period spacing patterns computed with GYRE v5.1 for the different rotation profiles. Right: The integrand of Eq. (3) (top) and the rotation kernel (bottom) for the pulsation mode with $(n, k, m) = (-1, -1, -1)$.

Fig. C.2. The 1.7 $M_\odot$ stellar model at $X_c = 0.1$ with $f_{\text{rot}, s} = 0.1 \, \text{d}^{-1}$ and $\delta f = 0.0$ (light grey), 0.4 (grey), and 0.8 (black), and the corresponding pulsations with $(k, m) = (+0, -1)$. Top left: the Brunt-Väisälä frequency profile. Middle left: The considered stellar rotation profiles. Bottom left: The period spacing patterns computed with GYRE v5.1 for the different rotation profiles. Right: The integrand of Eq. (3) (top) and the rotation kernel (bottom) for the pulsation mode with $(n, k, m) = (-35, +0, -1)$. 