The following full text is a preprint version which may differ from the publisher's version.

For additional information about this publication click this link.
http://hdl.handle.net/2066/157919

Please be advised that this information was generated on 2019-09-07 and may be subject to change.
GW150914: The Advanced LIGO Detectors in the Era of First Discoveries

B. P. Abbott et al.

(LIGO Scientific Collaboration and Virgo Collaboration)

(February 12, 2016)

Following a major upgrade, the two advanced detectors of the Laser Interferometer Gravitational-wave Observatory (LIGO) held their first observation run between September 2015 and January 2016. With a strain sensitivity of $10^{-22}/\sqrt{\text{Hz}}$ at 100 Hz, the product of observable volume and measurement time exceeded that of all previous runs within the first 16 days of coincident observation. On September 14th, 2015 the Advanced LIGO detectors observed a transient gravitational-wave signal determined to be the coalescence of two black holes [1], launching the era of gravitational-wave astronomy. The event, GW150914, was observed with a combined signal-to-noise ratio of 24 in coincidence by the two detectors. Here we present the main features of the detectors that enabled this observation. At full sensitivity, the Advanced LIGO detectors are designed to deliver another factor of three improvement in the signal-to-noise ratio for binary black hole systems similar in masses to GW150914.

PACS numbers: 04.80.Nn, 95.55.Ym, 95.75.Kk, 07.60.Ly

Introduction — On September 14th, 2015, both Advanced LIGO detectors in the USA, H1 in Hanford, Washington and L1 in Livingston, Louisiana, made the first direct measurement of gravitational waves [1]. The event, GW150914, was determined to be the merger of two black holes, with masses of $36 M_\odot$ and $29 M_\odot$, into a black hole of approximately $62 M_\odot$ [2]. 3.0 solar masses of energy ($\approx 5.4 \times 10^{47}$ J) was radiated in gravitational waves. The gravitational waves from this event, which occurred at a distance of $\approx 410$ Mpc $\approx 1.3 \times 10^9$ light years, changed the separation between the test masses by $\approx 4 \times 10^{-18}$ m, about one 200th of a proton radius.

The Advanced LIGO detectors, multi-kilometer Michelson-based interferometers [3], came online in September 2015, after a major upgrade targeting a factor of 10 sensitivity improvement over initial detectors [4]. While not yet at design sensitivity during their first observation run, they have already exceeded the strain sensitivity of the initial detectors across the entire frequency band, significantly surpassing the past discovery potential [5–10]. This paper describes the Advanced LIGO detectors, as well as their current and final design sensitivity, at the inception of gravitational-wave astronomy.

Astrophysical Reach — In general relativity, a gravitational wave far from the source can be approximated as a time-dependent perturbation of the space-time metric, expressed as a pair of dimensionless strain polarizations, $h_+$ and $h_\times$ [11]. An interferometric gravitational-wave detector acts as a transducer to convert these space-time perturbations into a measurable signal [12]. The interferometer mirrors act as ‘freely falling’ test masses. Advanced LIGO measures linear differential displacement along the arms which is proportional to the gravitational-wave strain amplitude. We define the differential displacement as $\Delta L = \delta L_x - \delta L_y$, where $L_x = L_y = L$ are the lengths of two orthogonal interferometer arms. The gravitational-wave strain and the interferometer displacement are related through the simple equation $\Delta L = h L$, where $h$ is a linear combination of $h_+$ and $h_\times$.

The tiny displacements induced by astrophysical events demand that the interferometer mirrors be free from environmental disturbances and require a highly sensitive interferometric transducer—designed to be limited only by disturbances arising from fundamental physics consideration. Since the interferometer response to displacement, or equivalently gravitational-wave strain, is frequency dependent, it is necessary to represent the limiting detector noises as functions of frequency normalized by the interferometer response.

The left panel of Figure 1 shows the amplitude spectral density of the total strain noise in units of strain per $\sqrt{\text{Hz}}$ during the first observation run (O1 run) and, for comparison, during the final science run of the initial LIGO detectors (S6 run). In the detectors’ most sensitive frequency band between 100 Hz and 300 Hz, the O1 strain noise is 3 to 4 times lower than achieved in the S6 run. At 50 Hz, the improvement is nearly a factor of 100.

The right panel of Figure 1 shows the single detector signal-to-noise ratio (SNR) for an optimally oriented compact binary system consisting of two $30 M_\odot$ black holes as a function of redshift $z$, and for different interferometer configurations. The observed strain amplitude is largest for a source whose orbital plane is parallel to the detector’s plane and is located straight above or below; we refer to such a source as optimally oriented. The SNR is computed in the frequency domain [13] using standard cosmology [15] and phenomenological waveforms which account for inspiral, merger and ringdown, but not spins [16].

A Michelson interferometer lacks good directional sensitivity to gravitational waves. The antenna pattern covers approximately half the sky, both above and beneath the plane of the detector. Moreover, the antenna patterns
of the two LIGO detectors are aligned to maximize the coincident detection of gravitational-wave signals, constrained to the 10 ms inter-site propagation time. The coincidence constraint substantially rejects non-Gaussian noise and vetoes local transients.

The observed strain amplitude is inversely proportional to the luminosity distance. For small redshifts, \( z < 1 \), the observable volume, and thus the detection rate, grows as the cube of the detector sensitivity. The number of detected events is expected to scale with the product of observing volume and observing time. Between September 12 and October 20 the H1 and L1 detectors had a duty cycle of 70% and 55%, respectively, while the observing time in coincidence was 48%. After data quality processing 17, 16 days of data were analyzed around GW150914, resulting in a time-volume product of 0.1 Gpc\(^3\)yr for binary black hole systems with masses similar to GW150914 18.

The Displacement Measurement — The current generation of advanced detectors uses two pairs of test masses as coordinate reference points to precisely measure the distortion of the space-time between them. A pair of input and end test masses is located in each of the two arms of a Michelson laser interferometer, as shown in Figure 2. The Advanced LIGO test masses are very pure and homogeneous fused silica mirrors of 34 cm diameter, 20 cm thickness and 40 kg mass.

It is critical that the test masses be free from sources of displacement noise, such as environmental disturbances from seismic noise, or thermally driven motion. These noise sources are most relevant at frequencies below 100 Hz, while shot noise of the optical readout is dominant at high frequency. Figure 3 shows the measured displacement noise of Advanced LIGO during the first observing run, together with the major individual contributions, as discussed below.

To minimize ground vibrations, the test masses are suspended by multi-stage pendulums 19, thus acting as free masses well above the pendulum resonance frequency of 0.4 Hz. Monolithic fused silica fibers 20 are incorporated at the bottom stage to minimize suspension thermal noise 21, which limits the useful frequencies to 10 Hz and above. The Advanced LIGO test masses require about 10 orders of magnitude suppression of ground motion above 10 Hz. The multi-stage pendulum system attenuates the ground motion by seven orders of magnitude. It is mounted on an actively controlled seismic isolation platform which provides three orders of magnitude of isolation of its own. 22, 23. Moreover, these platforms are used to reduce the very large displacements produced by tidal motion and microseismic activity. Tidal forces can produce displacements up to several 100 \( \mu \)m at frequencies around 0.15 Hz—even far inland.

The entire test mass assembly including the suspension system and part of the seismic isolation system resides inside an ultra-high vacuum system, with pressures typically below 1 \( \mu \)Pa over the 10,000 m\(^3\) volume, to prevent acoustic shorting of the seismic isolation systems and to minimize Rayleigh scattering in the optical readout.

The test masses are also susceptible to changes in the local gravitational field caused by changing mass distributions in their vicinity. While not limiting presently, at design sensitivity this time-dependent Newtonian noise...
The predicted levels for seismic, thermal and Newtonian noise sources are summarized in Figure 3 and compared to the total measured displacement noise. They are currently not limiting the sensitivity due to the presence of other technical noise sources, as detailed in Ref. [34].

Quantum noise in the interferometer arises from the discrete nature of photons and their Poisson-distributed arrival rate [35–37]. The momentum transfer of individual photons hitting a test mass gives rise to radiation pressure noise. Quantum radiation pressure noise scales as $1/m f^2$, where $m$ is the mass of the mirror and $f$ the frequency, and therefore it is most significant at lower frequencies.

Photon shot noise arises from statistical fluctuations in the photon arrival time at the interferometer output, and it is a fundamental limit of the transducer in sensing changes of the differential arm length. The importance of shot noise decreases as the inverse square-root of the laser power circulating in the interferometer arms. During the first observing run, Advanced LIGO was operating with 100 kW of circulating laser power. The corresponding quantum noise curve, comprising both low frequency radiation pressure noise and high frequency shot noise, is shown in Figure 3; it is limiting at frequencies above 100 Hz. In the upcoming years, we plan to increase the circulating laser power up to 750 kW, and thus reducing the shot noise contribution.

Coincident detection between the two LIGO observatories is used to reject transient environmental disturbances. Both observatory sites deploy seismometers, accelerometers, microphones, magnetometers, radio receivers, weather sensors, AC-power line monitors, and a cosmic ray detector for vetoes and characterization of couplings [38].

**Interferometric Transducer** — The Advanced LIGO detector uses a modified Michelson laser interferometer to translate strain into an optical phase shift [3]. Similar to an electromagnetic receiver, the optimal antenna length for a gravitational-wave detector is a quarter wavelength. For a gravitational wave at 100 Hz this is 750 km. The Advanced LIGO interferometer arms are 4 km long and employ an optical resonator between the input and end test masses that multiplies the physical length by the effective number of round-trips of the light. However, the physical length cannot be arbitrarily short, because test mass displacement noises are multiplied by the same factor.

The output port of the Michelson interferometer is held at an offset from a dark fringe, resulting in a small amount of light leaving the output port [39]. A differential optical phase shift will then decrease or increase the amount of light, depending which interferometer arm is momentarily stretched or squeezed by a passing gravitational wave. This light signal is measured by a photodetector, digitized and calibrated [40], before being sent to the analysis pipelines [41, 42].

The calibration factor that converts detected laser light power to mirror displacement is measured by applying a known force to a test mass [43]. An auxiliary 1047-nm wavelength laser is reflected off the end test mass and modulated in intensity to generate a varying force. The response of the optical transducer is measured by sweeping the modulation frequency through the entire detection band. It is also tracked by a set of fixed frequency lines. This way, the calibrated strain readout is
The Advanced LIGO detector uses coupled optical resonators to maximize the sensitivity of the interferometric transducer. These optical resonators enhance the light power circulating in each arm while simultaneously optimizing the effective antenna length and the gravitational-wave signal bandwidth [47–51]. As the interferometer is held near a dark fringe, most of the light is reflected back to the laser source. Adding a partially transmissive mirror at the interferometer input forms an optical resonator, leading to a power gain of 35 to 40 at the beamsplitter. The optical resonator in the interferometer arms enhances the circulating power by another factor of 300. Thus, 20 W of laser power entering the interferometer results in nearly 100 kW circulating in each arm. A partially reflective mirror is also placed at the output port to enhance the signal extraction and to increase the detector bandwidth. The resulting differential pole frequency or detector bandwidth is \( \simeq 335 \text{ Hz (H1)} \) and \( \simeq 390 \text{ Hz (L1)} \) [34].

All of these coupled optical resonators require servo controls to be brought and held on resonance [52]. The lengths of the optical resonators in the interferometer arms are stabilized to less than 100 fm, whereas the lengths of the other coupled resonators are kept within 1 to 10 pm [53]. Similarly, the interferometer test masses are aligned within tens of nanoradians relative to the optical axis for optimal performance. The noise arising from sensing and control of these extra degrees-of-freedom are combined together in the curve labeled “other DOF” in Figure 9. The Pound-Drever-Hall reflection locking technique is used to sense the auxiliary longitudinal degrees-of-freedom [53, 54], while an interferometric wavefront sensing scheme is deployed for the alignment system [55, 56]. Digital servo systems are used to feed control signals back to actuators which steer the relative longitudinal positions and orientations of the interferometer mirrors. To prevent reintroducing ground motion onto the test masses, electrostatic actuators [57] are mounted to a second quadruple pendulum known as the reaction chain. Only test masses use reaction chains; all other interferometer mirrors use coil actuators mounted on a rigid structure surrounding the suspensions.

Servo controls are also necessary for damping the plethora of normal modes of the pendular suspensions and for stabilizing the seismic isolation system to an inertial reference frame. Moreover, at high laser power, optical springs introduce angular instabilities due to photon radiation pressure-induced torques acting on the mirrors [58, 59], while the mirror acoustic modes introduce parametric instabilities [60, 61]. At the current laser power only one acoustic mode is unstable which can be tuned away by the ring heaters. Together with thermal heating, angular optical springs and multiple parametric instabilities are the main challenges that need to be overcome to increase the circulating laser power; both will require active damping for stable operations.
Overall, more than 300 digital control loops with bandwidths spanning from sub-Hz to hundreds of kHz are employed to keep each Advanced LIGO interferometer operating optimally during observation. The digital controls computers also serve as the data acquisition system that continuously writes on the order of $10^5$ channels of time series data to disk, at a rate of $\approx 12$ MB/s. It is synchronized to GPS to better than $10\mu$s [10]. A state-based automation controller provides hands-free running during operations.

**Outlook** — The global gravitational-wave network will be significantly enhanced in the upcoming years. In 2016 Advanced LIGO will be joined by Advanced Virgo, the 3km detector located near Pisa, Italy [62]. The Japanese KAGRA interferometer [63] and a possible third LIGO detector in India [64] will provide a global network that allows for improved parameter estimation and sky localization [65]. Achieving design sensitivity with the network of current detectors will define earthbound gravitational-wave astrophysics in the near future. Looking further ahead, we can envision current technologies leading to a factor of two improvement over the Advanced LIGO design sensitivity [11], so that events such as GW150914 could be detected with SNRs up to 200. More dramatic improvements will require significant technology development and new facilities.

**Acknowledgement** — The authors gratefully acknowledge the support of the United States National Science Foundation (NSF) for the construction and operation of the LIGO Laboratory and Advanced LIGO as well as the Science and Technology Facilities Council (STFC) of the United Kingdom, the Max-Planck-Society (MPS), and the State of Niedersachsen/Germany for support of the construction of Advanced LIGO and construction and operation of the GEO600 detector. Additional support for Advanced LIGO was provided by the Australian Research Council. The authors gratefully acknowledge the Italian Istituto Nazionale di Fisica Nucleare (INFN), the French Centre National de la Recherche Scientifique (CNRS) and the Foundation for Fundamental Research on Matter supported by the Netherlands Organisation for Scientific Research, for the construction and operation of the Virgo detector and the creation and support of the EGO consortium. The authors also gratefully acknowledge research support from these agencies as well as by the Council of Scientific and Industrial Research of India, Department of Science and Technology, India, Science & Engineering Research Board (SERB), India, Ministry of Human Resource Development, India, the Spanish Ministerio de Economía y Competitividad, the Conselleria d’Economia i Competitivitat and Conselleria d’Educaçió, Cultura i Universitats of the Govern de les Illes Balears, the National Science Centre of Poland, the European Commission, the Royal Society, the Scottish Funding Council, the Scottish Universities Physics Alliance, the Hungarian Scientific Research Fund (OTKA), the Lyon Institute of Origins (LIO), the National Research Foundation of Korea, Industry Canada and the Province of Ontario through the Ministry of Economic Development and Innovation, the Natural Science and Engineering Research Council Canada, Canadian Institute for Advanced Research, the Brazilian Ministry of Science, Technology, and Innovation, Russian Foundation for Basic Research, the Leverhulme Trust, the Research Corporation, Ministry of Science and Technology (MOST), Taiwan and the Kavli Foundation. The authors gratefully acknowledge the support of the NSF, STFC, MPS, INFN, CNRS and the State of Niedersachsen/Germany for provision of computational resources.

This document has been assigned the LIGO Laboratory document number LIGO-P1500237.

* Full author list given at the end of the article.

Electromagnetically coupled broadband gravitational antenna


Electromagnetically coupled broadband gravitational antenna


S. M. Aston et al., “Update on quadruple suspension design for Advanced LIGO,” Class. Quantum Grav. 29, 235004 (2012)


A. V. Cumming et al., “Design and development of the advanced LIGO monolithic fused silica suspension,” Class. Quantum Grav. 29, 035003 (2012)


S. Wen et al., “Hydraulic external pre-isolator system for LIGO,” Class. Quantum Grav. 31, 235001 (2014)


G. M. Harry et al., "Titania-doped tantala/silica coatings for gravitational-wave detection," Class. Quantum Grav. 24, 405 (2007)


E. Goetz et al., “Precise calibration of LIGO test mass actuators using photon radiation pressure,” Class. Quantum Grav. 26, 245011 (2009)


R. Schilling, (personal communication).


56 L. Barsotti, M. Evans, and P. Fritschel, “Alignment sensing and control in Advanced LIGO,” Class. Quantum Grav. 27, 084026 (2010).

57 C. Affeldt et al., “Advanced techniques in GEO 600,” Class. Quantum Grav. 31, 224002 (2014).


