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Basic Properties of Class Hierarchies regarding Probability Distributions

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Abstract

Concepts from object orientation have been applied to many fields to facilitate solving complex real-world problems. Medicine is an example of such a complex field, where, however, also the modeling of uncertainty is of major importance. It is our belief that object orientation can also play a role in the medical field to make representing and reasoning with uncertain knowledge easier. However, there is little known about how ideas from object orientation affect the specification and use of probability distributions. In this paper it is studied in what way structured probabilistic models can be organized in class hierarchies. We will provide a theoretical foundation of probabilistic models with object orientation, which are called probabilistic class hierarchies. This is expected to offer a basis for the modeling of complex problems, such as those in medicine, from which the examples used in this paper come.

Keywords: class hierarchies, probabilistic networks, object-oriented models, disease modeling.

1 Introduction

The aim of this paper is to explore ideas around class hierarchies as known from object-oriented languages in probabilistic graphical models, and in particular we are interested in whether this makes specification of probabilistic graphical models easier. Most other object-oriented probabilistic languages have so far refrained from using ideas of class hierarchies, with the exception of [2], [4] and [6]. However, in these papers using class hierarchies for the specification of probability distributions has no implications for the associated probability distributions. As in these previous papers, we will use Bayesian networks to represent probability distributions.

In our paper, we extend standard class hierarchies toward probabilistic class hierarchies by defining probability distributions for classes in hierarchies. It is first explored in what way class hierarchies can be extended from a probabilistic point of view. It will appear that the knowledge represented in a class hierarchy poses insufficient constraints to obtain a probabilistic class hierarchy straight away. However, by associating probability distributions to classes it will become clear that it is possible to obtain sensible constraints to these probability distributions. The wish to obtain such results was the main motivation why we started with this research. Some basic properties of probabilistic class hierarchies are examined, which lead us to a promising method to deal with complex problems, such as in medicine, the example domain of this paper.

The paper is organized as follows. The research discussed in this paper was motivated by the difficulty in the medical field to represent uncertain knowledge of multiple diseases, as is illustrated in Section 2. In Section 3, some basic notions from standard class hierarchies and probability theory are recalled. The new concept of a probabilistic class hierarchy, which is a standard class hierarchy combined with probability distributions, is introduced in Section 4. This section also contains the important properties we have been able to derive. Further conclusions and future work are discussed in Section 5.
2 Motivating Example

During the past decade, the presence of multiple disease, also known as multimorbidity, has become an increasingly important health-care problem in the modern, western society. In particularly, multimorbidity is the norm in the elderly patient. Unfortunately, medical knowledge whether contained in clinical guidelines or medical textbooks, is mostly organized around single disorders. That is why there are no guarantees whether an elderly patient receives appropriate treatment. Probabilistic graphical models support modeling knowledge of the interaction between multiple diseases, both in terms of manifestations and treatment actions and their effects, and also support the modeling of the temporal aspects of clinical guidelines. For instance, Figure 1 shows the graphical representations of knowledge about hypertension and dementia, with the vertices representing variables and arcs representing interactions between variables. We use different gray levels to categorize those variables. However, which interactions exist between these two disorders is not clear even though the models share some variables. Furthermore, a disadvantage of using a graphical representation of multiple diseases that does show such interactions is that it will become very complicated. The same holds for the associated probability distributions. There is, thus, a strong need to add levels of abstractions and means for reuse to Bayesian network representation in medicine, hence the notion of probabilistic class hierarchies developed in this paper.

3 Preliminaries

In this section, we review the standard theory of class hierarchies [1] and probability distributions [3].

3.1 Class Hierarchies

Classes and the relationships between classes are the starting point for any form of object orientation. Let $U$ be a set of all classes, called the *universe*. We write $c' \lesssim c$ to indicate that class $c'$ is a subclass of class $c$. Note that $\leq$ possesses the properties of a partial order, i.e. reflexivity, transitivity and antisymmetry. A proper subclass relation $\prec$ is a weak partial order that, in contrast to $\leq$, possesses irreflexivity and asymmetry.

Classes are used to define generic objects. These objects have properties that are shared by their instances. Such properties are defined by means of *attributes*, basically functions from classes to other classes. For class $c$ with $n$ attributes, we use the notation $c(a_1: c_1, \ldots, a_n: c_n)$ meaning that $a_i$ is an attribute of class $c$ having $c_i$ as a type, or a class as we will say. We call them *class structures*. Classes may have no attribute at all, and then we write $c()$. $A_c$ is used to denote the associated set of the attributes of $c$, e.g. $A_c = \{a, a'\}$ if we have $c(a : c', a' : c'')$. For a class with no attribute, i.e. $c()$, $A_c$ is defined as $A_c = \{\epsilon\}$, where $\epsilon$ denotes the empty attribute. An attribute may occur in multiple classes, but is unique within any class.
A class hierarchy $H$ is defined as a triple $H = (C, \preceq, S)$, where $S$ is the set of the class structures associated with the classes in $C$, and the partial order $\preceq$ represents subclass relations. Given two classes $c, c' \in C$ in a class hierarchy $H$ with $c' \preceq c$, then $c'' \preceq c'$ holds for all attribute $a \in A_c$ with the class structures $c(a : c'')$ and $c(a : c')$.

In the end, classes and class structures are meant to act as templates for instantiation, yielding instances. Instances of a class are meant to represent individual objects in the real world. For instances of objects, we use the notation $i(a = i')$ given class structure $c(a : c')$, where $i$ is an instance of class $c$ and $i'$ is an instance of $c'$. The instance-class relationship is denoted by $i \ll c$.

A path is a sequence $\sigma$ of attributes, which yields meaningful class information. The concatenation of the empty attribute $\epsilon$ with any attribute yields again the attribute, i.e., $a.\epsilon = a$. The paths of attribute $a$ with respect to class $c$, denoted by $\rho_c(a)$, are defined as:

$$\rho_c(a) = \begin{cases} \{a, \sigma \mid \sigma \in \rho_c(a')\} & \text{if } c(a : c') \in S; \\ \{\epsilon\} & \text{otherwise.} \end{cases}$$

For instance, if we extend the above-mentioned class structures with $c''(a' : c'''')$, then the paths of $a$ with respect to $c$ is $\rho_c(a) = \{a, a.\epsilon\}$. We can categorize the paths of an attribute with respect to a class into extendable paths and non-extendable paths. All paths with infinite length are extendable paths, the paths with finite length can be extendable, but can also be non-extendable. If the class structure of $c''$ is $c''(a' : c)$ instead of $c''(a' : c''')$, then the set of the paths of $a$ with respect to $c$ is infinite, i.e., $\rho_c(a) = \{a, a.\epsilon, a.a.\epsilon, a.a.a.\epsilon, \ldots\}$. We call the attributes having classes with no attributes basic attributes. The non-extendable paths are the paths terminating with basic attributes. The final classes of an attribute $a$ with respect to $c$ are the classes of the last attributes on the finite paths of $a$. Obviously, all final classes of non-extendable paths have no attributes.

The interpretation of a class without attributes, denoted by $\Gamma(c)$, translates to a set, e.g., $\Gamma(\text{nat}) = \mathbb{N}$, i.e., the set of natural numbers. The domain of an attribute $a$ with respect to class $c$, denoted by $\delta_c(a)$, is the Cartesian product of the interpretations of the non-extendable paths’ final classes of this attribute with respect to $c$. The interpretation of a class with attributes is equivalent to the Cartesian product of the domains of all attributes with respect to this class, formally, $\Gamma(c) = \times_{a \in A_c} \delta_c(a)$. Given the classes $c$ and $c'$ with $c' \preceq c$ and $A_c$ as the set of the attributes of $c$, then $\delta_c(a) \subseteq \delta_{c'}(a)$ holds for all $a \in A_c$, as a basic property of class hierarchies. Given two classes $c$ and $c'$ in the same class hierarchy, then $c' \preceq c \Rightarrow \Gamma(c') \subseteq \Gamma(c)$ always holds. Therefore, $c' \prec c \Rightarrow \Gamma(c') \subsetneq \Gamma(c)$ also holds. In this case, there exists at least one attribute, e.g., $a$ with $\delta_c(a) \subsetneq \delta_{c'}(a)$. We call such attributes the characteristic attributes of $c$ regarding $c'$. We say that classes $c$ and $c'$ are mutually exclusive, if $\Gamma(c) \cap \Gamma(c') = \emptyset$ holds. The union of two mutually exclusive classes $c$ and $c'$ is denoted by $c \cup c'$. Given a class $c$ and a finite set of its subclasses $C$, the subclass set $C$ is a partition of class $c$, if the equation $c = \bigcup_{c' \in C} c'$ holds.

### 3.2 Probability Theory and Bayesian Networks

The set of all possible outcomes of an experiment is called the sample space, denoted by $\Omega$. An event $E$ is a subset of the sample space $\Omega$, but not all the subsets of $\Omega$ are events. The collection of events can be considered as a subcollection $\mathcal{F}$ of the set of all subsets of $\Omega$. We call a collection of subsets of $\Omega$ a $\sigma$-field, denoted by $\mathcal{F}$, if it includes the empty set, the union of all subset of $\mathcal{F}$ and the complement of all member of $\mathcal{F}$. A real-valued random variable is a function $X : \Omega \to \mathbb{R}$ with the property that $\{\omega \in \Omega : X(\omega) \leq x\} \in \mathcal{F}$ for each $x \in \mathbb{R}$. We use upper case letters, e.g., $X$, to represent random variables, and lower case letters, e.g., $x$, to represent a specific values of $X$. The random variable $X$ is called discrete if it takes values in some countable subset of $\mathbb{R}$. The discrete random variable $X$ has probability mass function $f : \mathbb{R} \to [0, 1]$ given by $f(x) = P(X = x)$. A cumulative distribution function of a random variable $X$ is a function $F : \mathbb{R} \to [0, 1]$ given by $F(x) = P(X \leq x)$. The random variable $X$ is called continuous if its distribution function can be expressed as $F(x) = \int_{-\infty}^{x} f(u) \, du$ with $x \in \mathbb{R}$ for some integrable function $f : \mathbb{R} \to [0, 1]$, called the probability density function of $X$. Let $E', E''$ and $E'''$ be three events, such that $E = E' \cup E''$. Now, from $E' \subseteq E$, it follows that $P(E') \leq P(E)$, as $P(E) = P(E') + P(E'')$. This basic property offers a natural start, but not more than that, to give a probabilistic interpretation to identical attributes of two subclasses of a given class (see below).
Given two sets of the random variables $X$ and $Y$, defined on the same probability space, the joint distribution of $X$ and $Y$ defines the probability of events in terms of both $X$ and $Y$: $P(X, Y)$. Given the joint distribution of $X$ and $Y$, the marginal distribution of $X$ is calculated by summing (for discrete random variables) or integrating (for continuous random variables) the joint probability distribution over $Y$. If $P(Y) > 0$, then the conditional probability that $X$ may occur given that $Y$ has occurred is defined as $P(X \mid Y) = P(X, Y) / P(Y)$. Sets of the random variables $X$ and $Y$ are called conditionally independent given the set of random variables $Z$ if the conditional probability of $X$ given $Y$ and $Z$ is the same as the conditional probability of $X$ given $Z$, i.e., $P(X \mid Y, Z) = P(X \mid Z)$. A conditional probability can be inverted using Bayes’ rule: $P(X \mid Y) = P(Y \mid X)P(X) / P(Y)$.

A Bayesian network [5] is a probabilistic graphical model, denoted by $B = (G, X, P)$, where $G = (V, E)$ is a directed, acyclic graph (DAG) with a set of vertices $V$ and an edge relation $E \subseteq V \times V$, $X$ denotes a set of variables, and $P$ is the joint probability distribution of $X$, factored according to the structure of $G$. There is a 1–1 correspondence between sets $V$ and $X$. The joint probability distribution of a Bayesian network can be calculated from the conditional probabilities using the chain rule.

## 4 Probabilistic Class Hierarchies

In the previous sections, we reviewed class hierarchies and probability theory. For standard class hierarchies, the property $\Gamma(c') \subseteq \Gamma(c)$ if $c' \preceq c$ is seen as the essential. In order to cope with the representation of uncertainty in such an object-oriented framework, we need to somehow associate classes and attributes with probability distributions. This will lead us towards probabilistic class hierarchies. In the following section, we will introduce ideas and examples on how class hierarchies can be associated to probability distributions. Subsequently, formal properties are studied.

### 4.1 Initial Ideas on Probabilistic Class Hierarchies

Koller and Pfeffer [4] use a so-called Bayesian network fragment in their object-oriented Bayesian networks, OOBNs for short, to describe the probabilistic relations between the attributes of an class. In the OOBN approach, a class with probability distributions is represented graphically by a DAG $G_c = (V_c, E_c)$, where $V_c$ represents the set of vertices labeled with the random variable corresponding to attributes of class $c$, i.e., $A_c$. $E_c \subseteq V_c \times V_c$ is the set of directed edges between the vertices, mirroring direct probabilistic interactions between attributes. The graph is a compact representation of the set of independencies that hold for the associated probability distribution $P_c$ of the random variables corresponding to the attributes of $c$, that is why we call the graph an independency structure. In this paper, we use an attribute $a$ of a class $c$ as index to the corresponding random variables, i.e., $X_a$, which are denoted by the attributes’ names initialized with capital letters in independency structures instead; and $x_a$ denotes a possible value of $X_a$.

The random variable corresponding to an attribute is a real-valued function mapping the domain of this attribute with respect to a class into the real line $\mathbb{R}$, i.e., $X_a : \delta_c(a) \rightarrow \mathbb{R}$. Thus, due to the ordering of the real numbers, a total order is defined on the domain of each attribute. Let $X_a$ and $X_{a'}$ be the random variables corresponding to the attributes $a$ and $a'$, respectively. Attribute $a'$ is a parent of $a$ with respect to class $c$, if there exists an arc from the vertex labeled with $X_{a'}$ to that labeled with $X_a$. We denote the set of parents of attribute $a$ with respect to class $c$ by $\pi_c(a)$. Let $x_a$ and $x_{a'}$ be a value of the random variables $X_a$ and $X_{a'}$, respectively, with $x_a, x_{a'} \in \mathbb{R}$. If $X_a$ is a discrete variable, the conditional probability distribution of $a$ with respect to class $c$ is equal to the probability mass function of $X_a$, i.e.

$$P_c(X_a = x_a \mid \{X_{a'} = x_{a'} \mid a' \in \pi_c(a)\}) = f_{c,a}(x_a \mid \{x_{a'} \in \pi_c(a)\}).$$

If $X_a$ is a continuous variable, the conditional probability distribution of $a$ with respect to class $c$ is equal to the cumulative distribution function of $X_a$, i.e.

$$P_c(X_a \leq x_a \mid \{X_{a'} = x_{a'} \mid a' \in \pi_c(a)\}) = F_{c,a}(x_a \mid \{x_{a'} \in \pi_c(a)\}).$$

The joint probability distribution of class $c$ is equal to the product of the conditional distributions of all attributes of $c$. Similar to ordinary Bayesian networks, the independency structure defines the factorization of the joint distribution $P_c(\{X_a \mid a \in A_c\})$ associated with the graph concerning class $c$. 

Example 4.1. First, we give an example of a joint probability distribution associated to a class. The class structure of class person is defined as person\(\text{age } : 0,127, \text{smoker } : \text{boolean, blood pressure } : 70,200\), where class boolean is without attributes and is thus interpreted as \(\Gamma(\text{boolean}) = \{\text{true}, \text{false}\}\). The independency structure \(G_p\) is shown in Figure 2(left); \(p\) is taken as an abbreviation of ‘person’; similar abbreviations are used for ‘age’, ‘smoker’, and ‘blood pressure’. Let \(X_a\) and \(X_s\) be the random variables corresponding to the attributes age and smoker. The conditional probability distribution of the continuous random variable \(X_b\) corresponding to attribute blood pressure with respect to class person is equal to the conditional cumulative distribution function of \(X_b\) with respect to class person, i.e., \(P_p(X_b \leq x_b | X_a = x_a, X_s = x_s) = F_{pb}(x_b | x_a, x_s)\). Therefore, the joint probability distribution of the random variables corresponding to the attributes of class person is equal to the joint cumulative distribution function of the random variables of class person, i.e., \(P_p(X_a = x_a, X_s = x_s, X_b \leq x_b) = P_p(X_b \leq x_b | X_a = x_a, X_s = x_s)P_p(X_a = x_a)P_p(X_s = x_s) = F_{pa}(x_a, x_s, x_b)\).

For understanding the remainder of this paper, it is also important to realize that the joint probability distribution for a class \(c\), i.e., \(P_c(\{X_a \in A\})\) should be interpreted as a probability distribution conditioned on a random variable of classes \(Y\), i.e., \(P_c(\{X_a \in A\}) = P(\{X_a \in A\} | Y = c)\), where \(Y = c\) means that the context of the distribution is class \(c\).

Let us assume that a class \(c\) can be partitioned into two mutually exclusive subclasses \(c’\) and \(c''\). What we would like to examine is under which conditions the subclasses relation carries over to a subclass relationship with probability distributions, where \(c' \preceq c\) may have some implications with respect to the relationship between \(P_c\) and \(P_{c’}\). The fact that \(c'\) and \(c''\) are both subclasses of \(c\) may also have consequences. We continue with the example.

Example 4.2. Let us partition the class person into two mutually exclusive probabilistic subclasses ‘hypertensive person’ and ‘non-hypertensive person’, with the class structures:

- hypertensive person\(\text{age } : 0,127, \text{smoker } : \text{boolean, blood pressure } : 95,200\), and
- hypertensive person\(\text{age } : 0,127, \text{smoker } : \text{boolean, blood pressure } : 70,95\).

We assume that these two subclasses have both the same attribute set as class person. In this case, the attribute blood pressure is the only characteristic attribute of class person regarding class hypertensive person and class non-hypertensive person. The structure of the class hierarchy is shown in Figure 2(right). We will use similar abbreviations as before for these additional classes, here ‘hp’ and ‘nhp’.

Since the attributes age, smoker and blood pressure are translated to random variables \(X_a\), \(X_s\) and \(X_b\), the original domains are transformed to real numbers, allowing us to compare the associated (joint) probability distributions. Assuming for the time being that the independence information is the same for the three classes, the joint probability distributions are \(P_c(X_a, X_s, X_b) = P_c(X_b | X_a, X_s)P_c(X_a)P_c(X_s)\) for \(c \in \{p, hp, nhp\}\). The joint cumulative distribution function of the random variables of \(c\) is \(F_c(x_a, x_s, x_b) = \sum_{a \leq x_a} \sum_{s \leq x_s} \int_{-\infty}^{x_b} f_c(u, v, w) du dv\), where \(f_c(x_a, x_s, x_b) = f_{c,b}(x_b | x_a, x_s)f_{c,a}(x_a)f_{c,s}(x_s)\) is the joint probability density function of the random variables of \(c\). \(f_{c,b}(x_b | x_a, x_s)\) is the conditional density distribution function of \(X_b\), and \(f_{c,a}(x_a)\) and \(f_{c,s}(x_s)\) are the marginal distributions of \(X_a\) and \(X_s\), respectively.

As specifications of joint mass and density functions, possibly as factors in a Bayesian network, are sufficient to obtain any probability distribution concerning any Boolean expression, they seem to offer a good foundation for the comparison of joint probability distributions of classes, illustrated in the following example. Recall that joint mass and density functions are always defined on the real numbers, and this renders it possible to compare such functions to each other.
Three classes is blood pressure \( \sigma \) non-hypertensive person a hypertensive person person distribution in all classes, denoted by Example 4.3. We continue elaborating the idea. We assume that attribute blood pressure obeys a normal distribution obeys the subclass relation between class person, in class attributes A Definition 4.5. classes are identical. Example 4.6. The probabilistic class hierarchy defined in the examples of Section 4.1 contains the set of Xs we gave an example of a probabilistic class hierarchy in Section 4.1 using the assumption that the probabilistic class hierarchy is defined as a tuple \( H_P = (C, \preceq, S, X, P) \), where \( X \) denotes the set of random variables corresponding to the attributes defined in S, \( P \) is the set of the joint probability distributions of each class \( c \in C \), and the definitions of \( C, \preceq \) and \( S \) remain the same as for standard class hierarchies \( H \).

Example 4.6. The probabilistic class hierarchy defined in the examples of Section 4.1 contains the set of random variables, i.e. \( X = \{ X_a, X_s, X_b \} \), and its associated set of the joint probability distributions with respect to all different classes, i.e., \( P = \{ P_p(X_a, X_s, X_b), P_{hp}(X_a, X_s, X_b), P_{nhp}(X_a, X_s, X_b) \} \). We gave an example of a probabilistic class hierarchy in Section 4.1 using the assumption that the conditional probability distributions of the random variable corresponding blood pressure with respect to all three classes obey the normal distributions with the same variance. In fact, the following lemma shows that an important, general property holds for any probability distribution.

Lemma 4.7. Given the classes \( c, c', c'' \) with \( c', c'' \preceq c \) and \( c = c' \cup c'' \), let \( X_a \) be the random variable corresponding to attribute \( a \in A_c \) then from \( P_c(X_a) \leq P_c(X_a) \) it follows that \( P_{c''}(X_a) \geq P_c(X_a) \), and vice versa, for \( X_a \) either discrete or continuous.

Proof. We first define the probability distribution of classes, denoted by \( P(Y) \). Let \( c', c'' \preceq c \) be subclasses of \( c \) that partition \( c \). Clearly, \( P(Y = c | E) = P(Y = c' | E) + P(Y = c'' | E) \), for any event \( E \) (including the empty one). We use the definition of probability distributions conditioned on classes: \( P_c(X_a) = P(X_a | Y = c) \). We wish to prove that from \( P_c(X_a) \leq P_c(X_a) \) it follows that \( P_{c''}(X_a) \geq P_c(X_a) \), and vice versa (where also \( \geq \) and \( \leq \) can be interchanged). Using Bayes’ rule: \( P(X_a | Y = c) = P(Y = c | X_a) P(X_a) / P(Y = c) \propto P(Y = c | X_a) / P(Y = c) \). Similarly, \( P(X_a | Y = c') \propto P(Y = c' | X_a) / P(Y = c') \), and \( P(X_a | Y = c'') \propto P(Y = c'' | X_a) / P(Y = c'') \). Important is to realize that in the proportionality expressions we left out the same constant: \( P(X_a) \). Now, let us assume that \( P_c(X_a) \leq P_c(X_a) \), then, as probabilities are positive numbers...
\[ P_a(X_a) \leq P_b(X_a) \Leftrightarrow P(Y = c' \mid X_a)/P(Y = c) \leq P(Y = c \mid X_a)/P(Y = c) \]
\[ \Leftrightarrow \alpha = P(Y = c' \mid X_a)/P(Y = c \mid X_a) \leq \beta = P(Y = c')/P(Y = c). \]

Note that \( 0 \leq \alpha \leq \beta \leq 1 \). Thus, \( P(Y = c' \mid X_a) = \alpha P(Y = c \mid X_a) \), from which follows that \( P(Y = c' \mid X_a) = P(Y = c \mid X_a) - P(Y = c' \mid X_a) = P(Y = c \mid X_a) - \alpha P(Y = c \mid X_a) \); and \( P(Y = c') = \beta P(Y = c) \), from which it follows that \( P(Y = c') = P(Y = c) - P(Y = c') = P(Y = c) - \beta P(Y = c) = (1 - \beta)P(Y = c) \).

We now need to compare \( P_a(X_a) \) and \( P_b(X_a) \). We have:
\[ P(X_a \mid Y = c') \propto P(Y = c' \mid X_a)/P(Y = c') = \frac{(1 - \alpha)P(Y = c \mid X_a)}{(1 - \beta)P(Y = c)}. \]

From \( 0 \leq \alpha \leq \beta \leq 1 \) it follows that \( (1 - \alpha)/(1 - \beta) \geq 1 \), and \( P(X_a \mid Y = c') \geq P(X_a \mid Y = c) \).

Hence, \( P_a(X_a) \geq P_b(X_a) \). The proof for \( P_a(X_a) \geq P_b(X_a) \) is similar.

Lemma 4.7 also holds if the partition of a class has an arbitrary size. Because of the equivalence between the probability distribution of a random variable and its distribution function, we obtain the following, weaker corollary, that, however allows to express a generic property.

**Corollary 4.8.** Given a class \( c \) which is partitioned into a set of classes \( C \), if \( X_a \) is the random variable corresponding to attribute \( a \), the following inequality of conditional cumulative distribution functions holds for all \( a \in A_c \) and \( x_{a'}, x_a' \in \mathbb{R} \):
\[ \min_{c' \in C} \{ F_{c', a}(x_{a'}) \mid \{ x_{a' \in \pi_j(a)} \} \} \leq F_{c, a}(x_a \mid \{ x_{a' \in \pi_j(a)} \}) \leq \max_{c' \in C} \{ F_{c', a}(x_{a'}) \mid \{ x_{a' \in \pi_j(a)} \} \}. \]

Furthermore, this property also applies to the joint cumulative distribution functions, so that
\[ \min_{c' \in C} \{ F_{c'}(\{ x_{a \in A_c} \}) \} \leq F_{c}(\{ x_{a \in A_c} \}) \leq \max_{c' \in C} \{ F_{c'}(\{ x_{a \in A_c} \}) \} \]
holds for all \( a \in A_c \) and \( x_a \in \mathbb{R} \).

A related question is whether we can actually derive probabilistic information from the subclasses for a given class. The following lemma concerns expected values of random variables for a partition of a given class \( c \).

**Lemma 4.9.** Let \( C \) be a partition of class \( c \) and \( \alpha_{c'} = P(Y = c') \) be the weight of the subclass \( c' \in C \) regarding class \( c \), with \( \sum_{c' \in C} \alpha_{c'} = 1 \). \( X_a \) denotes the random variable corresponding to attribute \( a \in A_c \), and the random variable \( Y \) determines the context of the distribution. The properties of the expected values of \( X_a \) with respect to class \( c \), denoted by \( E_c(X_a) \), are:
- \( E_c(X_a) = \sum_{c' \in C} \alpha_{c'} E_{c'}(X_a) \), if \( X_a \) is discrete and \( E_{c'}(X_a) = \sum_{x_{a'}} x_{a'} P_{c'}(X_a = x_{a'}) \) is the expected value of \( X_a \) with respect to class \( c' \), where \( P_{c'}(X_a = x_{a'}) \) is the probability distribution of \( X_a \) with respect to \( c' \);
- \( E_c(X_a) = \int_{\mathbb{R}} x_a f(x_a) \, dx_a = \sum_{c' \in C} \alpha_{c'} \int_{\mathbb{R}} x_a f_{c'}(x_a) \, dx_a \), if \( X_a \) is continuous. \( f_c(x_a) \) and \( f_{c'}(x_a) \) are the density functions of \( a \) with respect to class \( c \) and class \( c' \), respectively.

**Proof.** Since \( C \) is a partition of \( c \), \( P(Y = c) = \sum_{c' \in C} P(Y = c') = 1 \). Therefore, \( \sum_{c' \in C} \alpha_{c'} = 1 \). If \( X_a \) is a discrete random variable, then
\[ E_c(X_a) = \sum_{x_{a}} x_{a} P(X_a = x_{a} \mid Y = c) = \sum_{x_{a}} x_{a} P(X_a = x_{a} \mid Y = c) P(Y = c) \] (as \( P(Y = c) = 1 \))
\[ = \sum_{x_{a}} x_{a} P(X_a = x_{a}, Y = c) = \sum_{c' \in C} \sum_{x_{a}} x_{a} P(X_a = x_{a}, Y = c') \] (as \( c = \bigcup_{c' \in C} c' \))
\[ = \sum_{c' \in C} \sum_{x_{a}} P(X_a = x_{a} \mid Y = c') P(Y = c') = \sum_{c' \in C} E_{c'}(X_a) P(Y = c') \]
\[ = \sum_{c' \in C} \alpha_{c'} E_{c'}(X_a) \] (as \( \alpha_{c'} = P(Y = c') \)).
The proof for a continuous random variable $X_a$ is analogous.

**Example 4.10.** We modify Example 4.3 by introducing the class *ordinary person* and the class *hypotensive person* to replace class *non-hypertensive person*. In this case, the class person is partitioned into three subclasses, i.e., class *hypertensive person*, *ordinary person* and class *hypotensive person*, in a probabilistic class hierarchy, renamed to hype, ordp and hypo, respectively. Let $X_a$ be the random variable corresponding to attribute age, we assume $E_{\text{hype}}(X_a) = 75$, $E_{\text{ordp}}(X_a) = 50$ and $E_{\text{hypo}}(X_a) = 40$. Let $\alpha_c$ with $c \in \{\text{hype}, \text{ordp}, \text{hypo}\}$ be the weight of $c$ corresponding to its superclass person, we assume $\alpha_{\text{hype}} = 0.2$, $\alpha_{\text{ordp}} = 0.5$ and $\alpha_{\text{hypo}} = 0.3$. Therefore, the expected value of $X_a$ with respect to class person is

$$E_p(X_a) = \alpha_{\text{hype}} \cdot E_{\text{hype}}(X_a) + \alpha_{\text{ordp}} \cdot E_{\text{ordp}}(X_a) + \alpha_{\text{hypo}} \cdot E_{\text{hypo}}(X_a)$$

$$= 0.2 \times 75 + 0.5 \times 50 + 0.3 \times 40 = 52.$$ 

5 Conclusion and Future Work

The aim of this research was to determine whether the concept of class hierarchy could be extended in a probabilistic fashion. There was clearly no straightforward way to extend class hierarchies in this way, but what has become clear is that definitions of class hierarchies do can have implications for probability distributions in the sense of the provision of constraints. We examined in this paper some basic properties of probabilistic class hierarchies by defining probability distributions in terms of classes and their attributes. We believe these properties may lead us to complete the existing approaches to probabilistic object-oriented modeling and establish a robust foundation for such models, which are considered to provide a promising method to solve a complex problem, especially in the medical field.

There are still questions in this research that remain unanswered. We will focus on two of such questions for future research. First, although we discovered the basic relations between the probability distributions of a class and the members of its partition, we wish to move further by looking for more specific relationships between actual distributions. Second, we only defined probabilistic class hierarchies with identical attribute sets for each class and its subclasses. While correct from a formal point of view, this property may make it hard to use such a probabilistic object-oriented model in practice. However, what we do expect is that such models may facilitate the analysis of databases, as we here start with some additional knowledge about relationship between instances found in the data. Our ultimate aim is to use such a formalism to handle representing and reasoning about multiple disease in multimorbidity as discussed in Section 2.

**References**


